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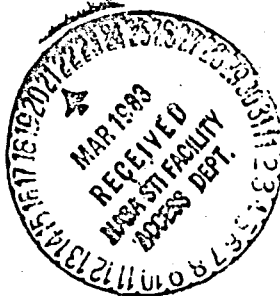
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Free Wake Techniques for Rotor
Aerodynamic Analysis; Volume No. III -
Vortex Filament Models

Michael Brower



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**Free Wake Techniques for Rotor
Aerodynamic Analysis; Volume No. III -
Vortex Filament Models**

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**National Aeronautics and
Space Administration**

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NOMENCLATURE

C_T	thrust coefficient
R	rotor radius
r	radius to vortex
w_z	induced velocity in wake in z direction
x	horizontal displacement
z	vertical displacement
Γ	circulation
Ω	rotational speed
ϵ	core size
$\Delta\theta$	defined in Fig. 1-2

SUMMARY

This report is Volume III of a three volume series entitled "Free Wake Techniques for Rotor Aerodynamic Analysis" and covering the following topics:

Volume I (Ref. 3) "Summary of Results and Background Theory" reviews the results obtained to date using both complete and simplified wake models and summarizes the theoretical background on which these models are based.

Volume II (Ref. 2) "Vortex Sheet Models" presents the results of computations using vortex sheets to model the wake and tests the sensitivity of the solutions to various assumptions used in the development of the models. The complete codings are included.

Volume III (present volume) "Vortex Filament Models" discusses results obtained using a vortex filament model, as opposed to sheets, again using various modelling techniques and including the computer codings.

INTRODUCTION

The application of computational fluid dynamics to the calculation of airloads on a hovering helicopter rotor is much more difficult than for an aircraft wing in steady flight. This is mainly because the trailing vortex geometry is more important to the induced velocities on a helicopter blade than on a wing. Whereas a wing in straight flight leaves its wake far behind, a hovering rotor gathers it beneath itself in a spiral that remains close to the blade. Thus the induced velocities must be calculated everywhere in the wake as well as on the blade in order to give the correct bound circulation. The close proximity of concentrated vortices often makes convergence slow and the results extremely sensitive to vortex core size and other parameters.

This report presents the results of airloads calculations for one case of a hovering rotor for which good experimental data are available. The method used allows the trailing wake geometry to evolve freely according to the velocities calculated at discrete control points in the wake. This is known as a free-wake method. A loop calculates in turn the induced velocities, the geometry

and the bound circulation, iterating until convergence is reached.

The method is loosely based on an original code written by J.D. Gohard (Ref. 1). That program has been developed by A. Tanuwidjaja (Ref. 2). In addition a simplified free-wake analysis has been done by R.H. Miller (Ref. 3 and 4) in which the wake immediately following the blade is made up of semi-infinite vortex lines and the wake beneath the blade consists of circular vortex rings. In order to reproduce the experimentally observed bound circulation both these programs require assumptions in calculating the wake geometry and core size in the first 180 degrees after the blade, as discussed in Ref. 4. This is a problem with the present method as well, as will be discussed in this report, and should become a focus of further research.

The program presented here is a rewritten version of the Tanuwidjaja-Gohard program. In describing the wake, vortex sheets have been eliminated in favor of concentrated vortex filaments; some other minor changes have been made, and the program has been "cleaned up" to make it less confusing and to remove parts no longer used.

Section 1 of this report presents the free-wake method in detail. Section 2 discusses the results of the program for the test case as different parameters are varied. The appendix contains the computer codes.

I. THE FREE-WAKE MODEL

1. Method

Each helicopter blade is treated as a concentrated line vortex of varying strength along the span. It is divided into discrete segments of constant vorticity where the strength of each segment is found from the angle of attack at its midpoint according to the formula:

$$\Gamma = \pi u a c$$

At the join of any two segments a trailing vortex is formed perpendicular to the blade with a strength equal to the difference in bound circulation on either side. (Figure 1-1). These trailing vortices are responsible for the downwash on the blade which, along with the blade pitch, give the angle of attack.

Since the wake moves down as the rotor turns, the trailing wake forms a helix beneath the rotor plane. Each trailing spiral vortex in the helix is divided into straight vortex segments of equal angular length joined end-to-end. Thus the actual length of a segment depends on its distance from the hub (Figure 1-2). The control points where induced velocities are calculated are on

the vortex lines where two segments meet. The location of a particular segment in the wake is found by integrating the velocities up to that point on the vortex line to which it belongs.

The whole wake is divided into three sections, the near, intermediate and far wakes (Figure 1-3). The near wake retains all the individual trailing vortices from the blade to obtain the best resolution in calculating the bound circulation. After some azimuthal angle, usually less than 90 degrees, the intermediate wake rolls up the near wake into three concentrated vortices. The strength of a rolled-up vortex is the sum of the strengths of the near wake vortices contributing to it; its first azimuthal position is the centroid of the last azimuthal positions of the same near wake vortices:

$$\vec{x} = \frac{\sum \vec{x}_i \cdot \Gamma_i}{\sum \Gamma_i}$$

After several blade revolutions the intermediate wake is replaced by the far wake. The far wake is modeled as three semi-infinite vortex cylinders corresponding to the three vortices in the intermediate wake. (For a discussion of the effects of far wake modeling see Ref. 5, p. 16.) The start of

the far wake is one vertical spacing underneath the last azimuthal station of the intermediate wake, and the radius is assumed to stay constant. There are no control points in the far wake and no induced velocities are calculated there.

The induced velocities due to the near and intermediate wakes are found using the Biot-Savart law for straight vortex segments with a correction for a viscous core size. The core allows the induced velocity to go to zero as a vortex line is approached instead of going to infinity. The induced velocity due to each segment in the wake and on the blade is calculated at every control point. These calculations consume the most computer time. A typical wake contains two hundred segments or 40,000 applications of the Biot-Savart relation for every iteration.

The induced velocities due to the far wake are found from an elliptic integral series solution used by Miller (Ref. 3).

The self-induced velocity of a straight vortex segment is zero if a finite core size is used. But the trailing vortices are really locally curved, and a correction to take this curvature into account is needed. This has been derived by Scully (Ref. 5) based on the self-induced velocity of a vortex ring of finite core size found by Lamb (Ref. 6). The formula is:

$$\omega_z = \frac{\Gamma}{4\pi r} (8 \cdot \ln(\frac{r}{\epsilon} \cdot \tan(\frac{\Delta\theta}{4})) - .25)$$

where $\Delta\theta$ is the angular length of the segments on either side of the control point. It is important to note that this is accurate only in cases where the arc length of the segments is large compared to their core size. This is true in the outer part of the wake where typical arc lengths are $0.1R$ and core sizes are $.01R$, but it becomes questionable closer to the root. The exact geometry close to the rotor hub is much less important to the bound circulation, however, and these corrections are small compared to the total induced velocities.

When overall convergence is finally reached, the main program calculates the lift coefficient. This coefficient, the final bound circulation and the wake geometry are compared with the experimental results.

2. Parameters

The important parameters to be varied in the program are the mesh sizes on the blade and in the near and intermediate wakes, the number of azimuthal stations in each wake, the criterion for

roll-up in the intermediate wake, the tip loss factor and the viscous core size.

a) Mesh Size

The usual practice is for the bound vortex segments on the blade to be long inboard and short near the tip where the circulation changes rapidly. In all the cases presented here, the distance between adjacent control points on the blade is $.02R$ from the ninety-percent span out to the tip, $.05R$ from the eighty-percent span to the ninety-percent span and $.1$ or $.15R$ over the rest of the blade. In all, thirteen control points (twelve segments) are used.

The near wake has the same number of trailing vortices as the number of bound segments requires; in this case, thirteen. The angular length of each segment is ten degrees. Usually the wake is carried 70 degrees after the blade. The intermediate wake is made up of twenty-degree segments and is usually carried about 740 degrees, or four blade passages, past the end of the near wake.

b) Roll-Up Criterion

The tip vortex in the intermediate wake is rolled up from the outermost trailing vortex in the near wake to the point of maximum circulation on the blade. The middle vortex is rolled up three stations in from where the tip roll-up ends, or about the 70% span. (As shown in Ref. 2, the solution is not sensitive to the exact definition of this station.) The root vortex is rolled up over the rest of the blade, excluding the innermost vortex of the near wake. It is found that eliminating the root vortex in the near wake tends to smooth out the distribution of bound circulation on the inner half of the blade and makes convergence easier.

c) Tip Loss

The tip loss factor compensates for the reduced lift at the very tip of the blade which is not well accounted for by the lifting line method. It simply sets the bound circulation at the last spanwise station equal to some fraction of the value it would have if the usual lifting line formula were used. This fraction is zero for all cases presented here, that is, the bound circulation of the last segment starting at 98% of the blade is set to zero; this is similar to the treatment of Ref. 7.

d) Viscous Core Size

not for
general
note

The core size is probably the most important single parameter. It has a very large effect on the velocity induced by vortex segments on nearby points. For example, if the core size of the tip vortex is set equal to $.02R$, this causes the bound circulation to go up at the last spanwise station because the tip vortex no longer induces enough downwash there to pull it down. It makes no difference to the circulation over the rest of the blade. In this study, a core size of $.01R$ is always used at the tip; it may be larger in the rest of the wake.

It is difficult to determine what core sizes should be used in the program, and few experimental guides are available. In general, the results seem overly dependent on the core. One area that should be studied is how the "proper" core size depends on the mesh size. In the example given above, if the distance between stations were made larger, a larger core size could be used (and vice-versa) and yet the true core size should not change. For a further discussion of the effect of core size on the tip vortex in the near wake see Ref. 4.

II. RESULTS

Table 1 shows the characteristics of the rotor being studied. The experimental data were published in Ref. 8.

a) Fundamental Solution

The "fundamental solution" uses a core size of $.01R$ throughout the wake. It carries the near wake over 70 degrees and the intermediate wake over 740 degrees. The solution is given in Figure 2-1 along with the experimental results; the bound circulation is plotted against the span and the tip vortex position is shown for every 180 degrees.

There are three major problems with the solution. One is that the bound circulation is too low from about the 70% span out to the tip. This gives a lift coefficient (C_L) of about $-.00448$ instead of the experimental value of $-.0046$. Another problem is that the tip vortex remains too close to the blade in the first 180 degrees. The third problem is that the wake defined by the tip vortex does not contract enough; it even begins to expand after 540 degrees.

b) Wake Contraction

no influence
on coefficient

The wake does not contract enough either because the intermediate wake produces too much radial velocity or because [the far wake produces too little. By removing the inner vortices in the intermediate and far wakes the wake contraction can be improved (Figure 2-2) but not without sacrificing bound circulation near the root, which yields a much lower lift coefficient. It is interesting to note that the circulation near the tip is unaffected. This implies that wake contraction has little to do with the rest of the problem.

c) Core Size (Near Wake)

The only way to raise the bound circulation near the tip is to increase the viscous core size in the near wake. All three parts of the wake, near, intermediate and far, contribute an important fraction of the downwash on the outer 25% of the blade. The far wake is too distant for any reasonable increase in the core size to have an effect. The core size of the intermediate wake can be important if it is larger than about $.04R$; this possibility, known as core burst, is discussed below. The near wake vortex segments are close enough for a small change in the core size to have a large effect.

The result of increasing the core size in the near wake (but not, as mentioned in Section 1, at the tip) from $.01R$ to $.02R$ is shown in Figure 2-3. The peak is higher and the tip vortex has accordingly moved down somewhat. The circulation in the "valley" between the 70% and 90% span is still too low.

d) Core Burst

It has been observed that a concentrated tip vortex passing close to a blade undergoes a sudden expansion of its core (Ref. 9). This fact can be exploited to improve the distribution of bound circulation. The intermediate wake tip vortex produces strong upwash on the blade from the 90% span out to the tip, and downwash everywhere else. Thus an increase in core size will at the same time raise the circulation in the valley and lower the circulation at the peak. This is illustrated in Figure 2-4, where the assumed core burst is to $.05R$ and the core size in the near wake is $.02R$. The wake geometry stays the same.

In order to raise the peak back up again, the core size in the near wake must be increased to $.05R$. (It quickly reaches the point where a larger near-wake core size makes no difference.) This is shown in Figure 2-5. This last solution is the best

obtained so far. The lift coefficient is $-.00453$, about two percent lower than the experimental value.

e) Tip Vortex Location

The deficiency in circulation between the 70% and 90% span is possibly caused by the tip vortex coming too close to the blade at first encounter. The "natural" location of the tip vortex predicted by the program is closer to the blade than was observed in Ref. 8. It may be that the slow downward motion of the tip vortex is caused by inadequate modeling of the roll-up in the near wake, possibly by not having enough trailing vortices at the tip.

One way to test this is to reduce the near wake azimuth to only ten degrees - essentially rolling up the tip vortex immediately. The results are shown in Figure 2-6 for the same case as Figure 2-5 (core burst to $.05R$ and near wake core size $.05R$). The circulation and the lift coefficient are slightly larger, and the tip vortex location is a little farther from the blade. The solutions for other combinations of parameters are similar. This suggests that poor modeling of the near wake roll-up could be part of the problem.

In the earlier results from this program using a near wake spanning seventy degrees, the problem of the tip vortex location was much worse. It was discovered that this was because the program had not been allowed to converge properly. The initial approximation to the wake geometry does not roll up the vortices in the near wake. During the first few iterations, the main trailing vortex actually moves up. If the convergence test for the geometry is not tight enough the program will converge before the near wake has had a chance to move back down. It usually takes over 60 iterations to converge within two percent.

CONCLUSIONS

The results of the program so far indicate that further investigation of the method is necessary. With a small core size, the bound circulation is too low on the outer part of the blade while the tip vortex passes too close at first encounter. The two problems are closely related. The slow descent of the tip vortex may be because of near wake modelling deficiency. Assuming a larger core size, corresponding to a burst vortex, results in better agreement with test data. A further area needing research is the relationship between the core size and the mesh size.

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- 5 M. Scully, "Computation of Helicopter Rotor Wake Geometry and Its Influence on Rotor Harmonic Airloads," MIT ASRL TR 178-1, March 1975.
- 6 H. Lamb, HYDRODYNAMICS, Dover, 1945.
- 7 W. Johnson, "Comparison of Calculated and Measured Model Rotor Loading and Wake Geometry," NASA TM 81189, April 1980.
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- 9 T.C. Biggers, A. Lee, K.L. Orloff and O.T. Lemmer, "Measurements of Helicopter Rotor Tip Vortices," American Helicopter Society Forum Proceedings, May 1977.

Table 1. ROTOR CHARACTERISTICS

Straight

Blades - 2

Twist - 11° Collective pitch at 75% Radius 9.8°

Solidity .0464

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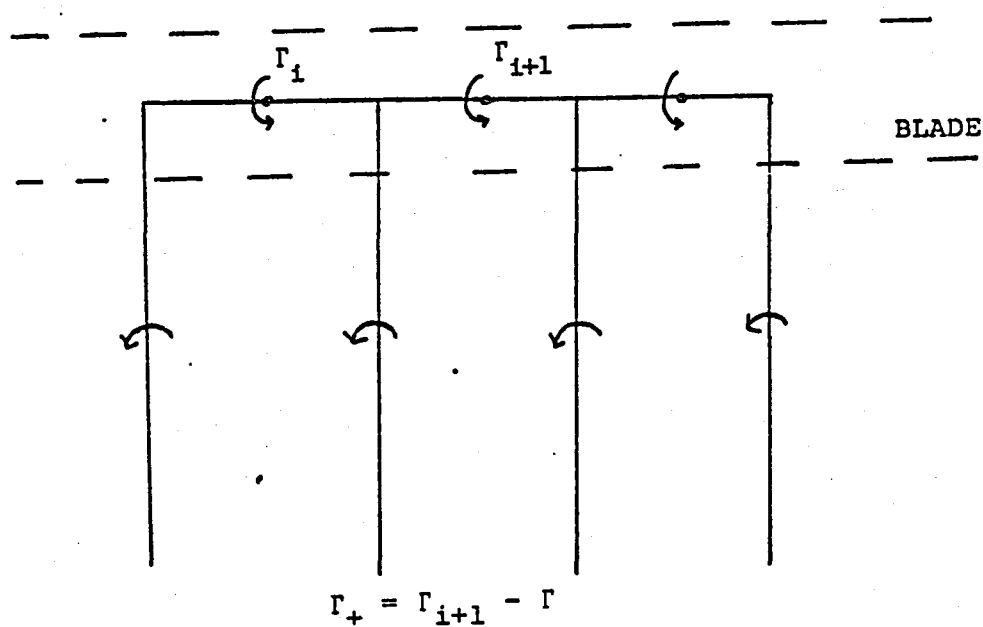


Fig. 1-1 Lifting line bound segments and trailing vortices.

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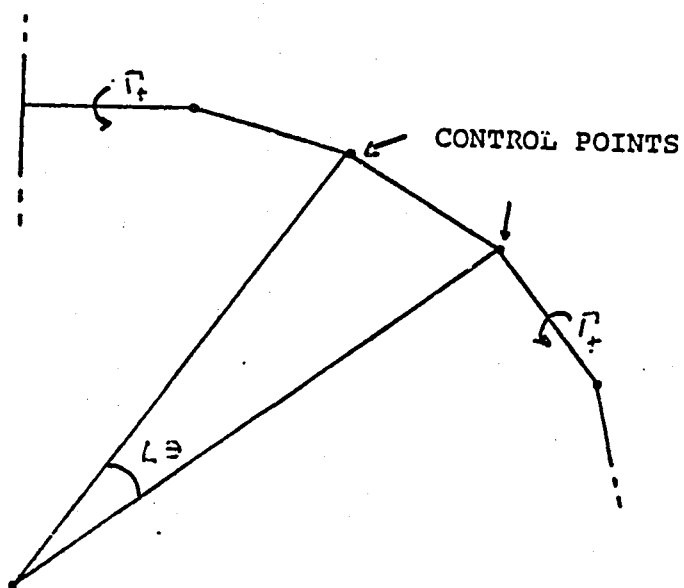


Fig. 1-2 Trailing vortices divided into straight segments.

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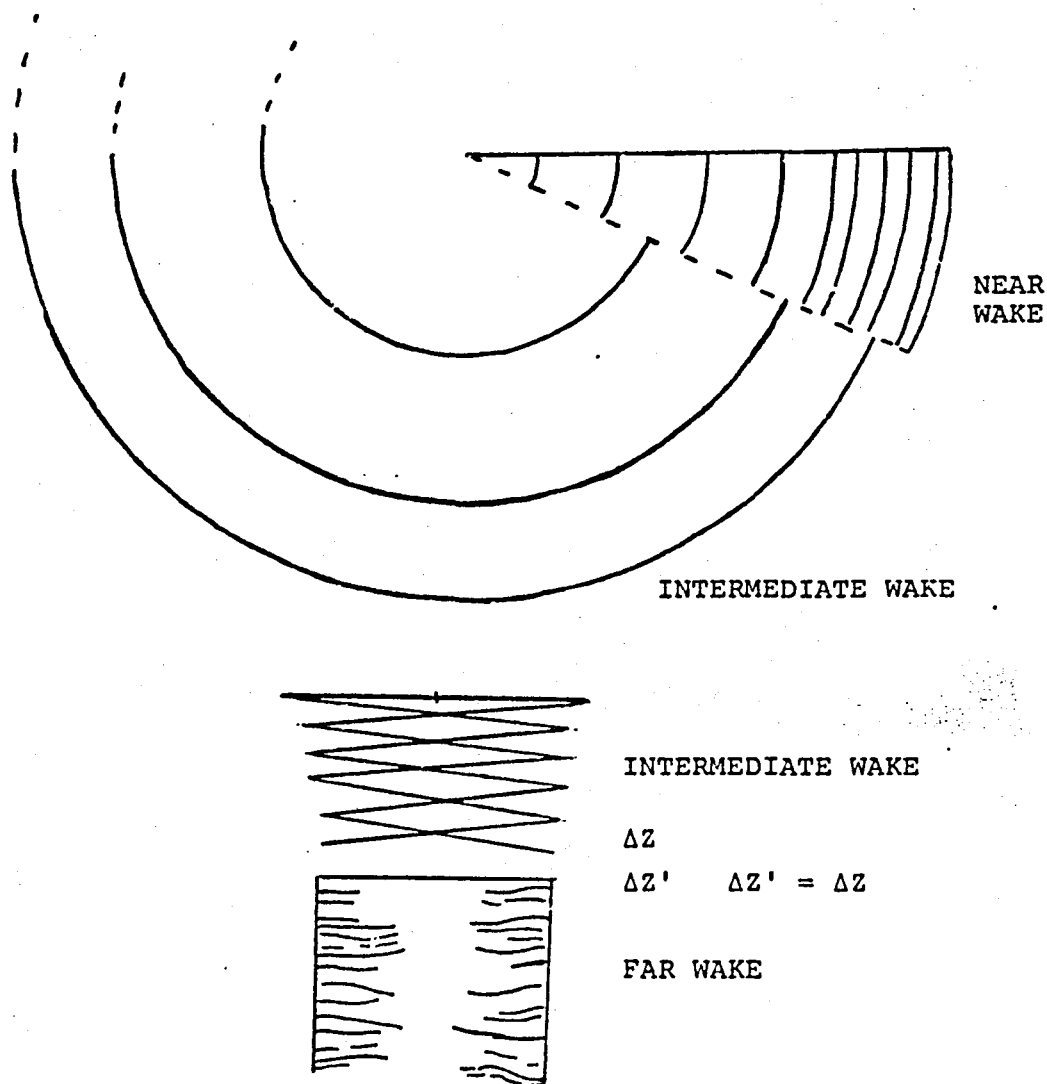


Fig. 1-3 Near, intermediate and far wakes.

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Fig. 2-1

Bound circulation distribution with core size of
.01R everywhere in wake. $C_T = .00452$

Near Wake extends to 70° , intermediate wake to 740°

○ Ref. 7

□ Computed

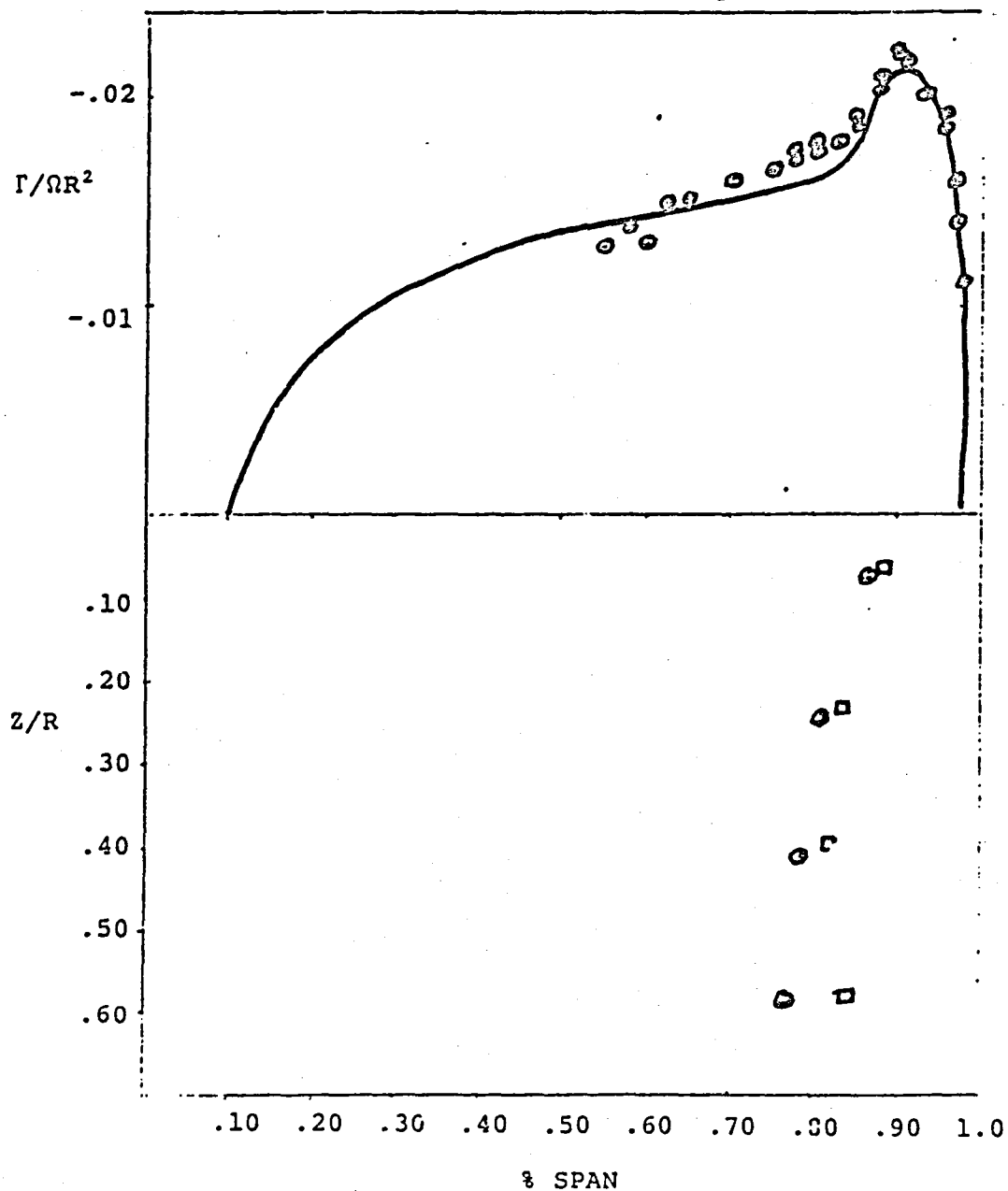
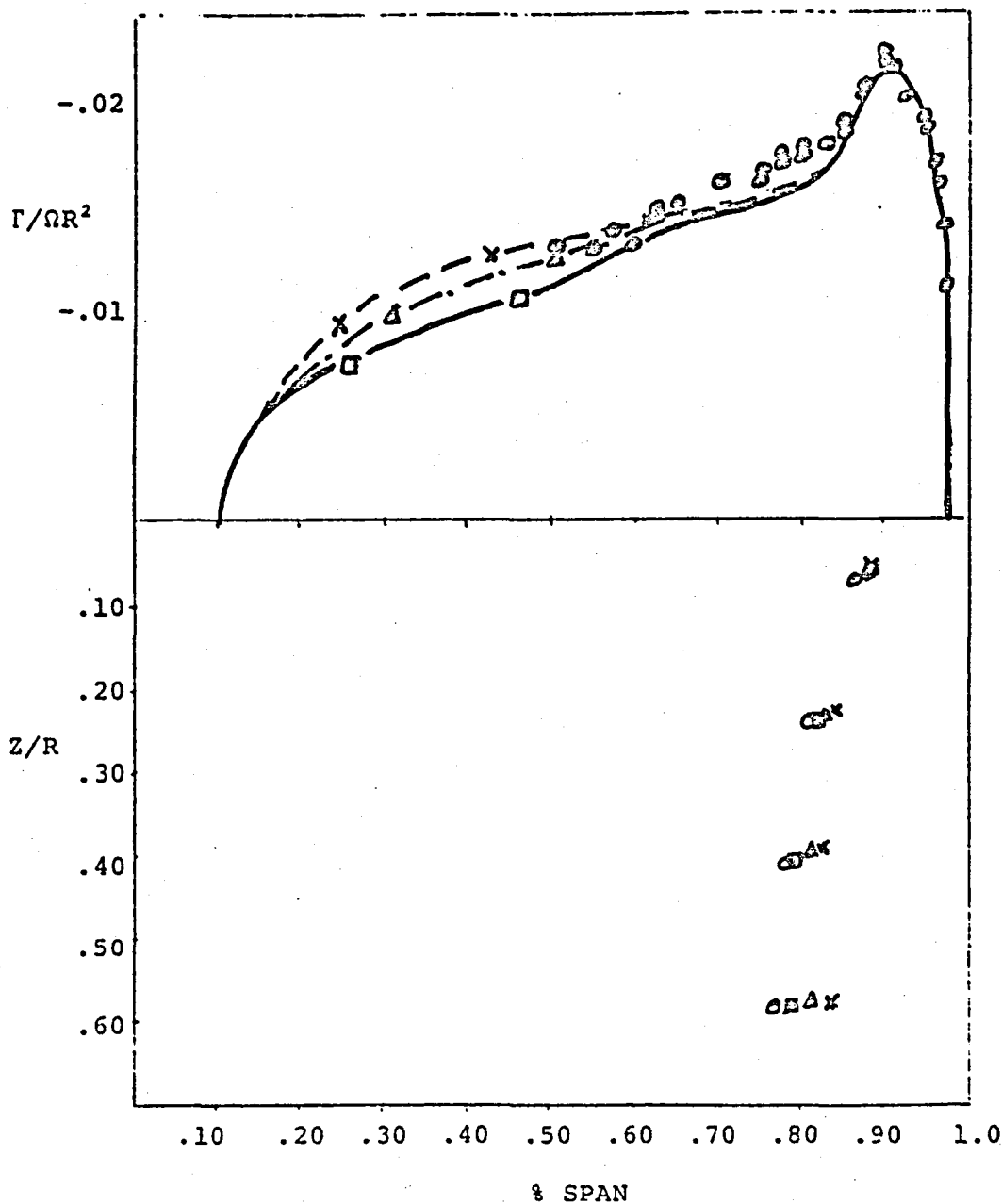


Fig. 2-2 Effect of inner wake on case of Fig. 2-1.

- Inner wake eliminated.
- △ Far wake, inner wake only eliminated.
- x Same as Fig. 2-1.
- Ref. 7



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Fig. 2-3 Effect of core size for case of Fig. 2-1.

$$C_T = .00452$$

Inner near wake core size of .02R

Tip vortex and intermediate wake of .01R

○ Ref. 7 □ Computed

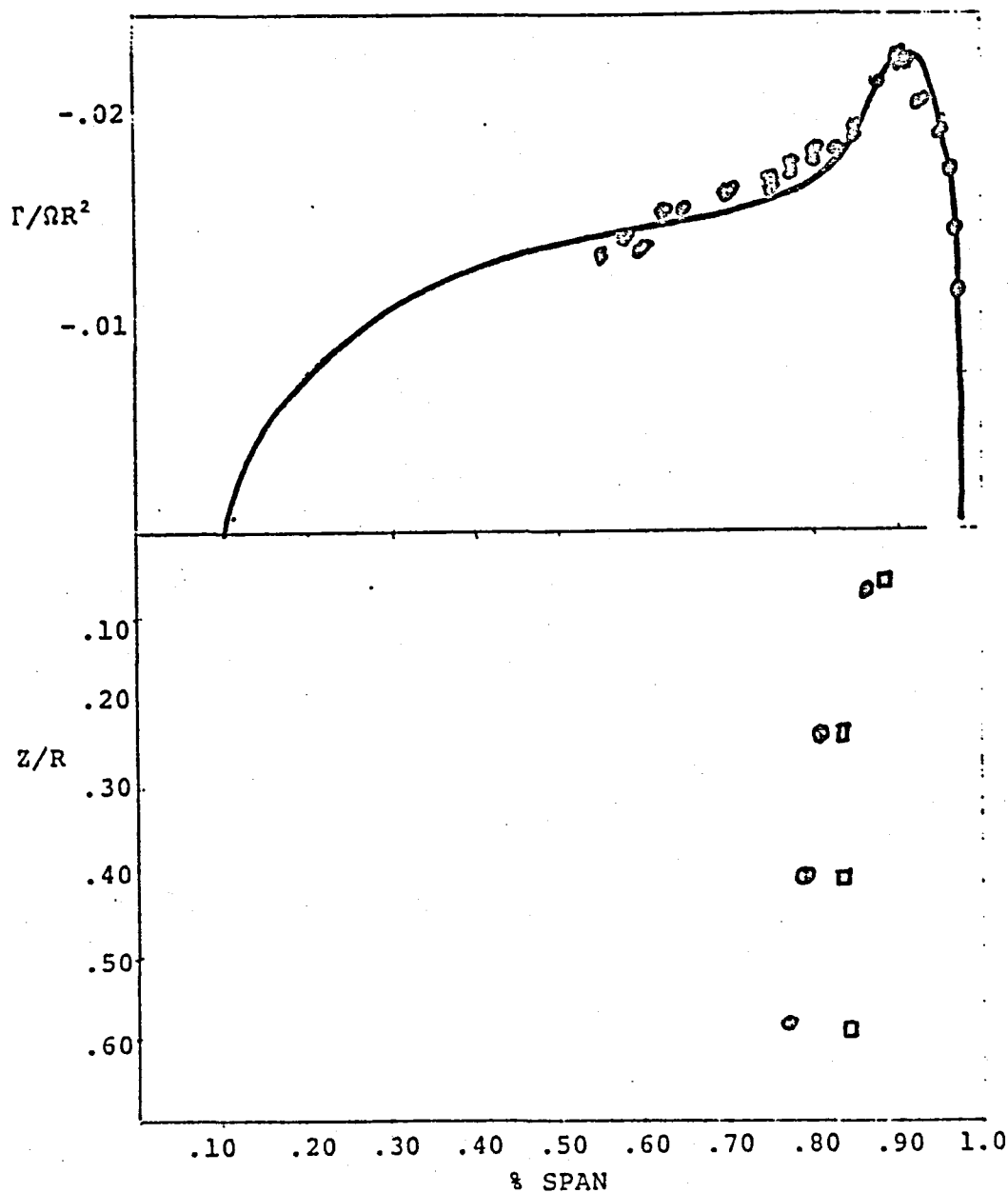
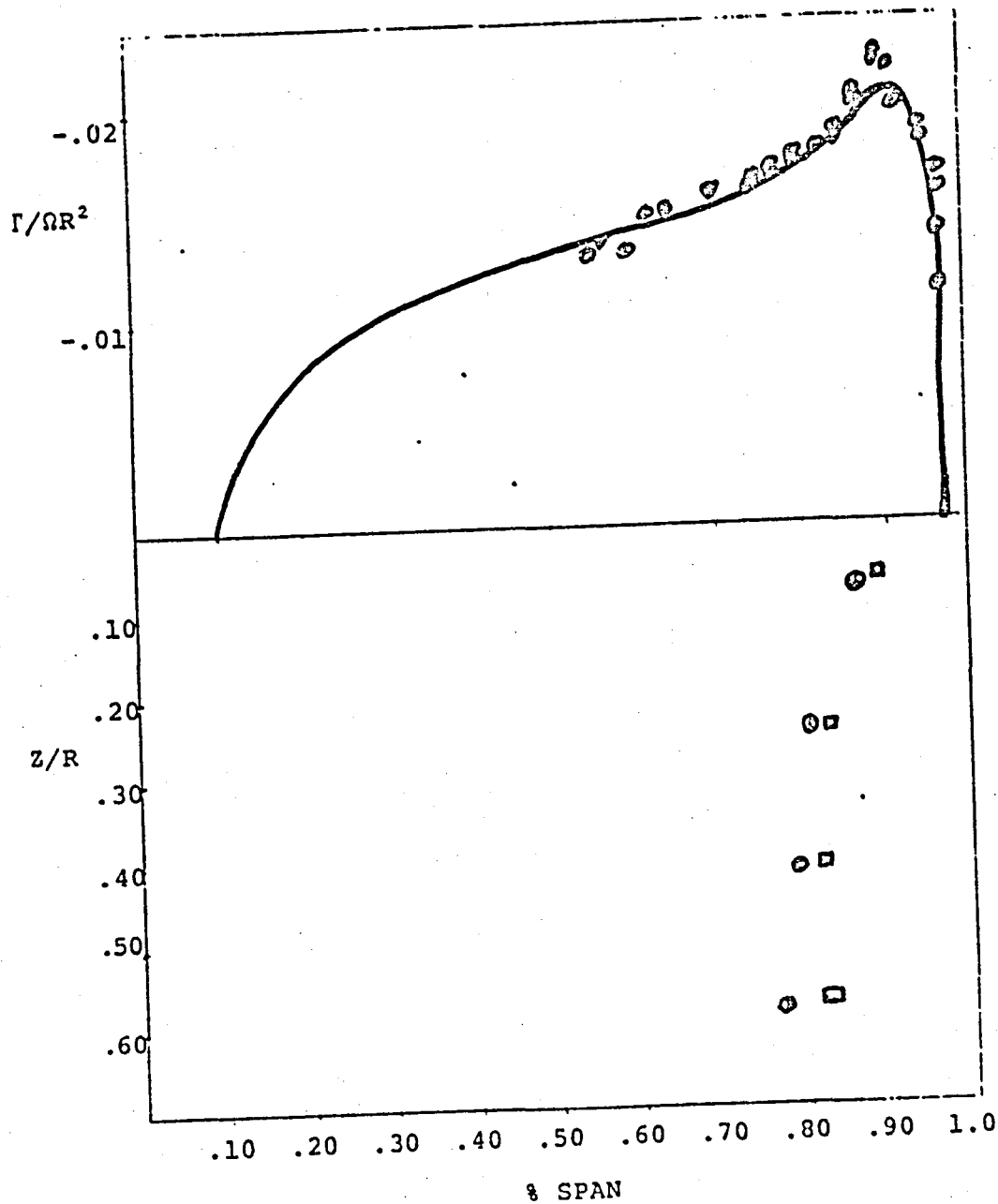


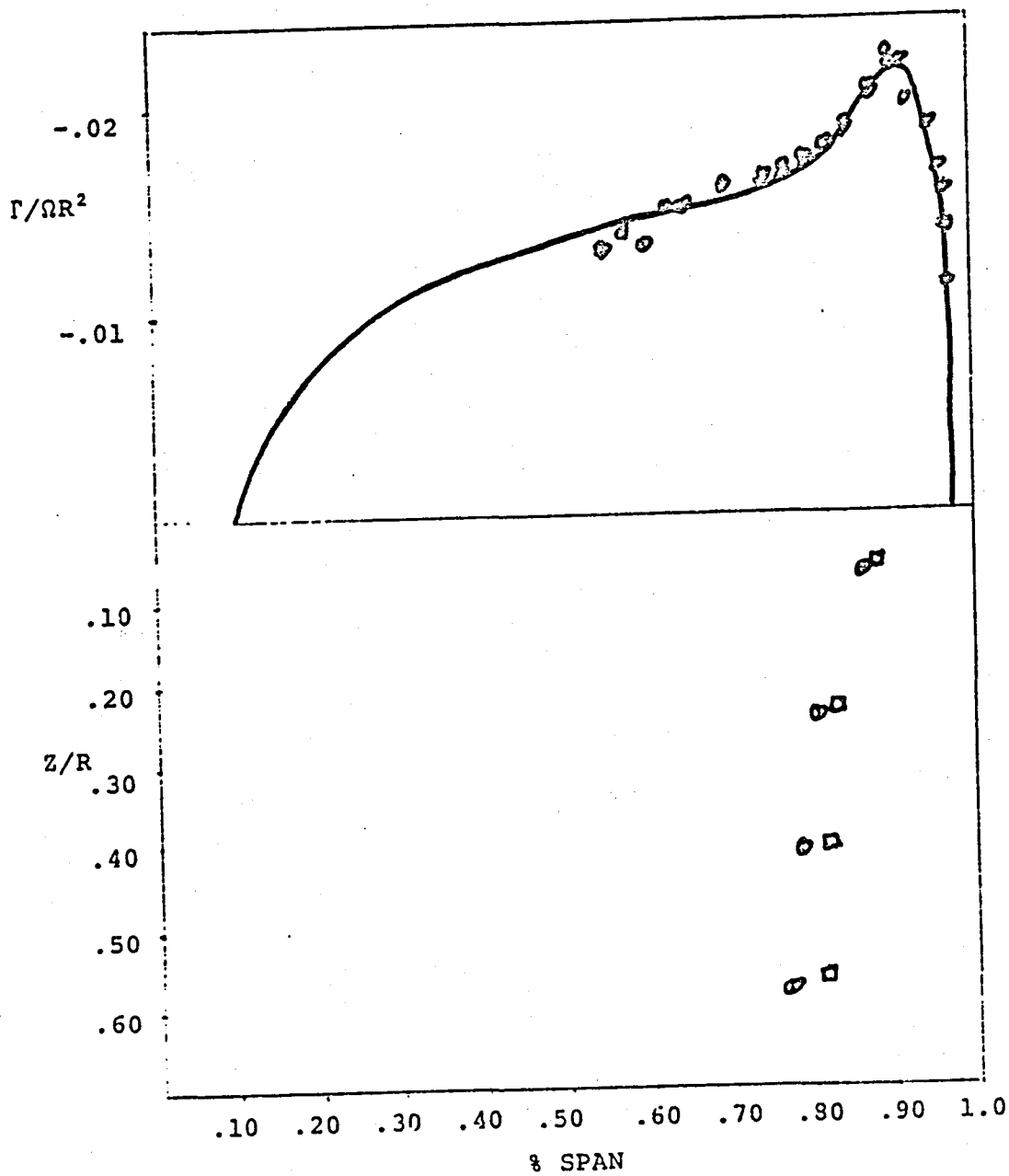
Fig. 2-4 Same as Fig. 2-3 but with "burst" tip vortex.
Core size of .05R in intermediate wake. $C_T = .00451$
○ Ref. 7 □ Computed



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Fig. 2-5 Same as Fig. 2-4 but with "burst" tip and inner intermediate wake. $C_T = -.00453$

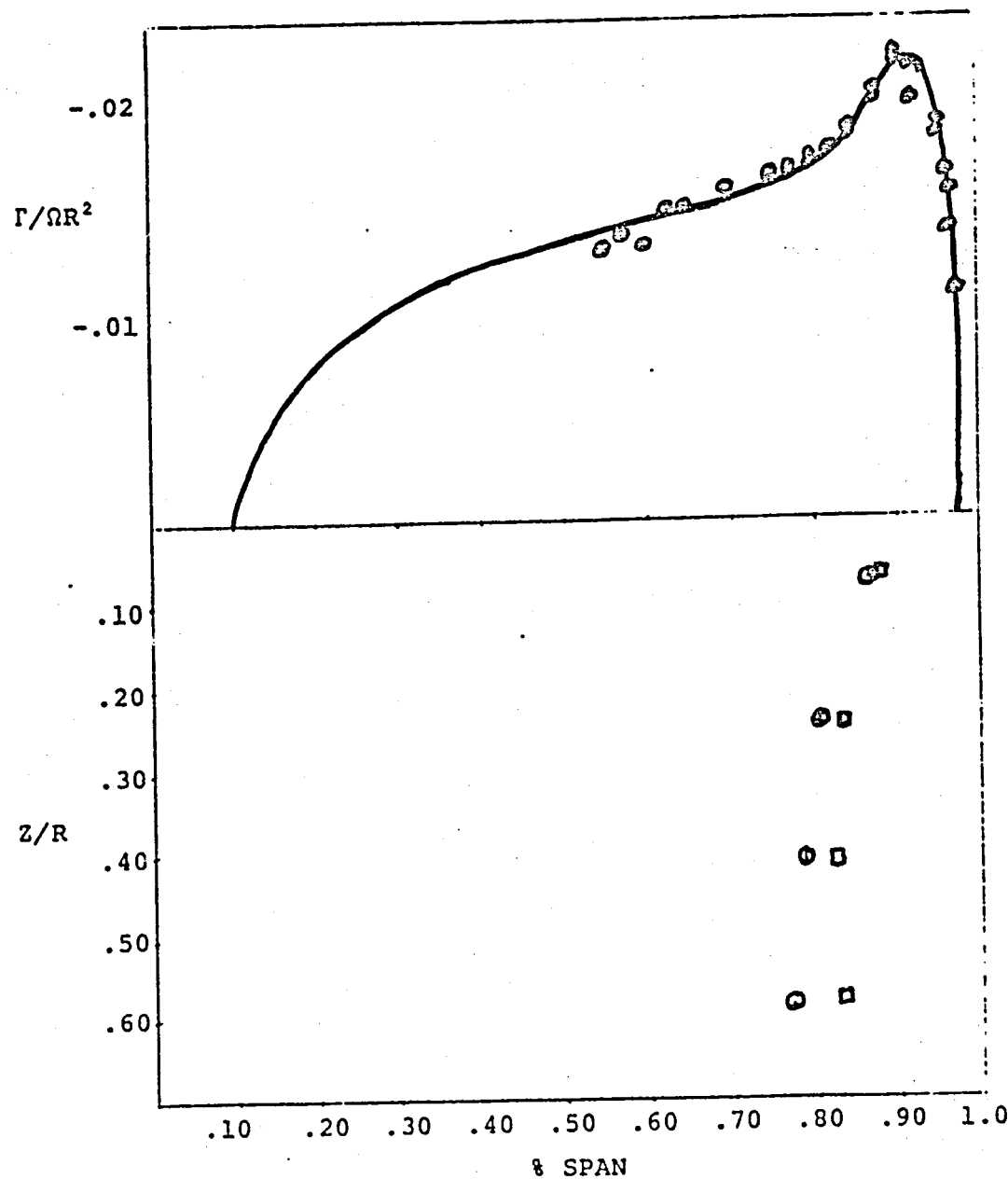
○ Ref. 7 □ Computed



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Fig. 2-6 Same as Fig. 2-5 but near wake extending to 10° only,
intermediate wake to 800° . $C_T = .00454$

○ Ref. 7 □ Computed



APPENDIX

LIST OF VARIABLES

Following is a list of important variables in the FreeWake program.

alp	angle of attack, $\text{alp} = \text{flamda} - \text{thetac}$
alphas	angle of attack at stall
blades	real number of blades
cd	(cd0,cdk) drag coefficients, $\text{cd} = \text{cd0} + \text{cdk} * \text{alp} * \text{alp}$
coeff	(coeff1) tip loss coefficient
dpsii	angular length of intermediate wake segments
dpsin	angular length of near wake segments
etanv	spanwise location of endpoints of bound segments
etaiv	initial spanwise location of intermediate wake trailing vortices
eta1 eta2 eta3	spanwise location of intermediate wake trailers
facgam	relaxation factor for LOOP1
facgeom	relaxation factor for INTGR
facvel	relaxation factor for LOOP2
flamda	inflow angle due to downwash on blade
fmu	net inflow -- used only for wind turbine cases

fps1 core size for near wake
 fps2 core size for tip vortex in near wake
 fps3 core size of intermediate wake (core burst)
 gamc bound circulation
 gamt trailing vortex strengths in near wake
 gamti rolled-up vortex strengths in intermediate wake
 gamtip same as gamti(3)

 int parameter for intermediate output: int=1 prints
 lift coefficient and wake geometry for every fifth
 iteration

 itest itest=0 if all subroutines have converged

 iwrite parameter for output: iwrite=0 gives only final
 results, iwrite=1 gives results for every iteration,
 iwrite=2 gives induced velocities from each part of
 wake (near, intermediate and far) for each iteration

 knnvr initial value of nnvr
 knivr initial value of nivr

 lim1 maximum number of iterations for LOOP1
 lim2 maximum number of iterations for main loop

 lp power coefficient, or drag integrated over span

 lt lift coefficient, or lift integrated over span

 nblds (nblds1) integer number of blades

 ncase number of different cases in file to be run

 niter current iteration number of main loop

 niva number of azimuthal stations in intermediate wake

 nivr number of spanwise stations in intermediate wake

nnva	number of azimuthal stations in near wake
nnvr	number of spanwise stations in near wake
sigma	solidity of rotor
theta	blade pitch at endpoints of bound segments
thetac	blade pitch at midpoints of bound segments
wxiv	x,y,z components of induced velocities in
wyiv	intermediate wake
wziv	
wxnv	x,y,z components of induced velocities in near
wynv	wake
wzmv	
xiv	x,y,z coordinates of control points in
yiv	intermediate wake
ziv	
xnv	x,y,z coordinates of control points in near wake
ynv	
zmv	

At the end of the computer code a sample output is given (for Figure 2-5) showing the lift coefficient, bound circulation, induced velocity on the blade and wake geometry.

The bound circulation (GAMC) and induced velocities (WXC, WYC, WZC) are given at the centers of the bound vortex segments whereas the trailing vortices (which give the wake geometry) are located at the ends.

The integer headings in the wake geometry refer to the azimuthal station number. The first line under each heading is the azimuthal angle (PSI), the second is the radius (R) and the third is the vertical distance (Z) from the rotor plane. The first azimuthal station is at the blade, so here $PSI=0.$, $Z=0.$ and R gives the spanwise positions of the ends of the bound vortex segments.

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Computer Codes

```

C * FREE-WAKE ANALYSIS OF A WIND TURBINE AERODYNAMICS
C * -----
C *
common/parm/iwr,ird,lms,lim1,lim2,niter,iwrite
common/geom/nblds1,nblds,sigma,fmu,etan(15),knnvr,eta1(6),knivr,
&lt;twist,thetad(15),theta(15),thetac(14),theta0,theta0d,alphas,
&cd0,cdk,dpsind,dpsin,dps1id,dps1i,coeff,coeff1,c,s,blades,
&nnvr,nnva,nnvr1,nnva1,hncr,hnca,etanv(15),etanc(16),
&nivr,niva,nivr1,niva1,nicr,nica,etaiv(6),etaic(7),
&ntva,ntva1,ntca,fps1,fps2
common/gamma/gamc(16),gamt(15),gamt1(3),gamtip,eta1,eta2,eta3,
&k1,k2,k3,facgam
common/posit/xnv(15,18),ynv(15,18),znv(15,18),xiv(6,50),yiv(6,50),
&ziv(6,50)
common/veloc/wxnv(15,18),wynv(15,18),wznv(15,18),wxiv(6,50),
&wyiv(6,50),wziv(6,50),facgeom
common/initial/wxc(14),wyc(14),wzc(14)
common/vindo/ifar,nfar,x1,x2,y1,y2,z1,z2,x,y,z,facvel,gm,ux,uy,uz
common/self/iself
common/loopsave/wxv(16),wyv(16),wzv(16)
common/special/itgr
common/extraspec/fps3
namelist/fparm/iwr,ird,lms,lim1,lim2,iwrite,nfar,ifar,gam,wx,wy,
&wz,facgam,facvel,facgeom,ncase,iself,int,itgr
real ltp,lp:lt
data pi/3,14159/
iwr=6
ird=5
iself=0
coeff=0.
nblds1=2
alphas=1.
coeff1=.5
lms=50
lim1=50
lim2=15
nfar=90
ifar=0
int=0
read(ird,fparm)
do 901 ncas=1,ncase
call input1(ncas)
if(fps3.ne.fps2) write(iwr,53) fps3
53 format(" CORE BURST TO ",f5.2)
if(ifar.eq.1) write(iwr,54)
54 format(" ELLIPTIC INTEGRAL FAR WAKE ")
write(iwr,57) coeff1
57 format(" TIP COEFFICIENT ",f5.2)
if(itgr.eq.1) write(iwr,58)
38 format(" ROLLED UP TRAILERS MEET AT POINT")
do 10 i=1,nnvr
et=etanv(i)
wxc(i)=wx*et*ot
wyc(i)=0.
wzc(i)=et*wz/.85
gamc(i+1)=gam*ot/.91
if(et.gt..91) wzc(i)=(wz*et/.85)*(1.-et)/.15
if(et.gt..91) gamc(i+1)=(gam*et/.91)*(1.-et)/.09
10 continue
wzc(nnvr)=wzc(nnvr-1)

```

gamc(nnvr)=0.
gamc(1)=0.
gamc(nnvr)=0.
call compa

C *
C *
C *
C *

MAIN LOOP

kwrite=iwrite
do 1 niter=1,11m2
itest=0
facgeom=.5
facvel=.3
if(niter.le.2) facgeom=1.
if(kwrite.eq.0) iwrite=0
fiter=niter/5.
fniter=float(niter/5)
if(fniter.eq.fiter.and.kwrite.eq.0) iwrite=1
if(niter.eq.1.and.kwrite.eq.0) iwrite=1
call loop2(ktest)
itest=ktest
call intgr(ktest)
itest=itest+ktest
call loop1(ktest)
itest=itest+ktest
if(itest.eq.0) goto 2
if(int.eq.1.and.iwrite.gt.0) goto 1003

1004
1
2
C *

continue
continue
continue

write(iwr,100) itest
write(iwr,108)
write(iwr,120) (gamc(i),i=1,nnvr)
write(iwr,120) (wxv(i),i=1,nnvr)
write(iwr,120) (wyv(i),i=1,nnvr)
write(iwr,120) (wzv(i),i=1,nnvr)
write(iwr,107)
do 150 j=1,nnva
write(iwr,109) j
write(iwr,120) (xnv(i,j),i=1,nnvr)
write(iwr,120) (ynv(i,j),i=1,nnvr)
write(iwr,120) (znv(i,j),i=1,nnvr)

150

continue
do 160 j=1,niva
write(iwr,109) j
write(iwr,120) (xiv(i,j),i=1,nivr)
write(iwr,120) (yiv(i,j),i=1,nivr)
write(iwr,120) (ziv(i,j),i=1,nivr)

160
1003

continue
it=0.
lp=0.
do 148 i=1,nnvr-1
et=.5*(atanv(i)+atanv(i+1))
wz=wzv(i)+fmu
wy=wyv(i)+et
flamda=atan(wz/wy)
u=sqrt(wz**2+wy**2)
alp=flamda-thetac(i)

```

cd=cd0+cdk*alp**2
if(abs(alp).gt.abs(alphas)) cd=2.*cd0+cdk*alp**2
lip=u*gamc(i+1)
tlip=lip*cos(flamda)
flip=-lip*sin(flamda)
dp=u*pi*(sigma/blades)*cd*.5
fdp=dp*cos(flamda)
tdp=dp*sin(flamda)
tp=tlip+tdp
fp=flip+fdp
lt=lt+tp*(etanv(i+1)-etanv(i))
lp=lp+fp*(etanv(i+1)**2-etanv(i)**2)
148 continue
lt=lt*blades/pi
lp=lp*blades/2./pi
write(iwr,106) lt,lp
if(int.eq.1.and.itest.ne.0.and.niter.lt.11m2) goto 1004
iwrite=2
call loop2(ktest)
901 continue
100 format(//," MAIN FINAL RESULTS -- CONVERGENCE:",14)
109 format(/,14)
108 format(/," GAMC,WXV,WYV,WZV:")
106 format(/," LT=",f10.6," LP=",f10.6)
107 format(//," WAKE GEOMETRY:")
120 format(2(9f10.6,/))
999 continue
stop
end

```

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```

subroutine input1(ncas)
common/parm/lwr, lrd, lms, lim1, lim2, niter, lwrite
common/geom/nbls1, nbls, sigma, fmu, etan(15), knnvr, etai(6), knivr,
&lt;twist, thetad(15), theta(15), thetac(14), theta0, thet0d, alphas,
&cd0, cdk, dpsind, dpsin, dpsiid, dpsii, coeff, coeff1, c.s, blades,
&nivr, nnva, nnvr1, nnva1, nnvr, nnca, etanv(15), etanc(16),
&nivr, niva, nivr1, niva1, nivr, nica, etai(6), etaic(7),
&ntva, ntva1, ntca, fps1, fps2
common/extraspec/fps3
equivalence (nnvr, nnvr1), (nivr, nivr1), (nnva, nnva1)
equivalence (niva, niva1), (nnvr1, nnvr2), (nivr1, nivr2)
name1st/case/nbls, sigma, knnvr, nnva, dpsind, etan, knivr,
&niva, dpsiid, etai, fmu, thetad, alphas, cd0, cdk,
&fps1, fps2, coeff1, fps3
data conv, twopi/.017453293, 6.283185308/

C *
read(lrd, case, err=999, end=888)
dpsin=dpsind*conv
dpsii=dpsiid*conv
do 11 i=1, knnvr
theta(i)=thetad(i)*conv
11 continue
blades=float(nbls)
c=cos(twopi/blades)
s=sin(twopi/blades)
77 continue
C *
nnvr=knnvr
nivr=knivr
nnvr=nnvr+1
niva=niva+1
nivr=nivr+1
niva1=niva-1
nnvr1=nnvr-1
nivr1=nivr-1
do 65 i=1, nnvr
etanv(i)=etan(i)
65 continue
do 66 i=1, nivr
etaiv(i)=etai(i)
66 continue
do 12 i=2, nnvr
etanc(i)=(etanv(i)+etanv(i-1))* .5
12 continue
do 13 i=2, nivr
etaic(i)=(etaiv(i)+etaiv(i-1))* .5
13 continue
etanc(1)=1.5*etanv(1)-.5*etanv(2)
etaic(1)=1.5*etaiv(1)-.5*etaiv(2)
etanc(nnvr)=1.5*etanv(nnvr)-.5*etanv(nnvr-1)
etaic(nivr)=1.5*etaiv(nivr)-.5*etaiv(nivr-1)
C *
nnva1=nnva-1
nnca=nnva+1
do 32 i=1, nnvr2
thetac(i)=theta(i)+(theta(i+1)-theta(i))*
&(etanc(i+1)-etanv(i))/(etanv(i+1)-etanv(i))
32 continue
if(nbls.lt.1.or.nbls.gt.8) goto 60
if(nnvr.gt.15.or.nnvr.lt.2) goto 60

```



```

      if(nivr.gt.6.or.nivr.lt.2) goto 60
      if(nnva.gt.18.or.nnva.lt.2) goto 60
      if(niva.gt.50.or.niva.lt.2) goto 60
      if(etanv(1).lt.0.) goto 60
      if(etanv(1).ne.etaiv(1)) goto 60
      if(etanv(nnvr).ne.1..or.etaiv(nivr).ne.1.) goto 60
      do 80 i=2,nnvr
      if(etanv(i).le.etanv(i-1)) goto 60
      continue
80    do 81 i=2,nivr
      if(etaiv(i).le.etaiv(i-1)) goto 60
      continue
81    if(fmu.lt.0.) go to 60
      write(iwr,150)ncas,nbids,sigma,fmu
150   format("1*** INPUT *** CASE # : ",i3,/,
      &" NUMBER OF BLADES",i2,/, " SIGMA",f12.5,/,
      &" MU",f12.5)
      write(iwr,162)(thetad(i),i=1,knnvr)
162   format(" PITCH ANGLE DISTRIBUTION(DG):",5f10.5,/,5x,6f10.5,
      &/,5x,4f10.5)
      write(iwr,153)alphas,cd0,cdk
153   format(" STALL ANGLE",f12.5,/, " CD=",f5.4,"+",f5.3,"*ALPHA**2")
      write(iwr,154)lms,lml,lmm2,fp31,fp32
154   format(" MAX. NUMBER OF ITERATIONS FOR SEMRI,LOOP1,LOOP2:",3i4,/,
      &" CORE SIZE FOR NEAR WAKE INBOARD: ",f6.3," TIP: ",f6.3)
      write(iwr,155)knnvr,nnva,(etan(i),i=1,knnvr)
155   format(" NEAR WAKE DEFINITION:(",i2,".",i2,").",4f10.5,
      &/,5x,6f10.5,/,4f10.5)
      write(iwr,156)knivr,niva,(etai(i),i=1,knivr)
156   format(" INT. WAKE DEFINITION:(",i2,".",i2,").",4f10.5,
      &/,5x,6f10.5,/,5x,4f10.5)
      return
999   write(iwr,200)
200   format(" *** INPUT *** ERROR ON (IRD) ")
      stop

C *
888   write(iwr,215)
215   format(" INPUT: END OF FILE ON (IRD)")
      stop
102   format(8f10.5)
122   format(3i2)
C *
60    continue
      write(iwr,181)
181   format(" *** INPUT *** DATA INVALID OR OUT OF RANGE ")
      write(iwr,case)
      stop

C *
      end

```

2: 2000 1000 100
1000 1000 100

```

subroutine compa
common/parm/lwr, lnd, lms, lmi, lfm2, niter, lwrite
common/geom/nbls1, nbls, sigma, fmu, etan(15), knvr, etai(6), kn
&lt;twist, thetad(15), theta(15), thetac(14), theta0, thetad, alphas
&cd0, cdk, dpsind, dpsin, dpsid, dpsil, coeff, coeff1, c, s, claden
&nnvr, nnva, nnvr1, nnva1, nnvr, nnca, etanv(15), etanc(16),
&nivr, niva, nivr1, niva1, nivr, nica, etai(6), etai(7),
&ntva, ntva1, ntca, fps1, fps2
common/posit/xnv(15, 18), ynv(15, 18), znv(15, 18), xiv(6, 50),
&yiv(6, 50), ziv(6, 50)
common/initial/wxc(14), wyc(14), wzc(14)
dimension wrn(15), wri(6), wzn(15), wzl(6)
equivalence (nnvr, nnvr1), (nivr, nivr1), (nnva, nnva1)
equivalence (niva, niva1), (nnvr1, nnvr2), (nivr1, nivr2)
data pi/3.14159/

c .
do 21 i=1, nnvr
xnv(i, 1)=etanv(i)
ynv(i, 1)=0.
znv(i, 1)=0.
phi=0.
r=etanv(i)
do 21 j=1, nnva-1
phi1=phi+dpsin
r1=r+dpsin*wxc(i)
xnv(i, j+1)=r1*cos(phi1)
ynv(i, j+1)=r1*sin(phi1)
znv(i, j+1)=znv(i, j)+dpsin*wzc(i)
phi=phi1
r=r1
21 continue
if(lwrite.lt.2) goto 103
write(lwr, 500)
500 format(/, ". INITIAL WAKE GEOMETRY:")
do 91 j=1, nnva
write(lwr, 505) j
write(lwr, 510) (xnv(i, j), i=1, nnvr)
write(lwr, 510) (ynv(i, j), i=1, nnvr)
write(lwr, 510) (znv(i, j), i=1, nnvr)
91 continue
103 continue
505 format(/, i4)
510 format(1x, 2(5x, 9f10.6, /))

c .
c . NODES AND VELOCITIES FOR THE INTERMEDIATE WAKE
c .

do 30 i=1, nivr
et=etaiv(i)
do 31 i2=2, nnvr
if(et.lt.etanv(i2)) goto 32
31 continue
32 continue
a=(etanv(i2)-et)/(etanv(i2)-etanv(i2-1))
wz1(i)=a*wzc(i2-1)+(1.-a)*wzc(i2)
wri(i)=a*wxc(i2-1)+(1.-a)*wxc(i2)
xiv(i, 1)=a*xnv(i2-1, nnva)+(1.-a)*xnv(i2, nnva)
yiv(i, 1)=a*ynv(i2-1, nnva)+(1.-a)*ynv(i2, nnva)
ziv(i, 1)=a*znv(i2-1, nnva)+(1.-a)*znv(i2, nnva)
psi=dpsin*(nnva-1)
r=sqrt(xiv(i, 1)**2+yiv(i, 1)**2)

```

```

do 22 j=1,nlva-1
  psi=psi+dpsi
  wrr=wrr(i)
  if(psi.gt.pi) wrr=wrr/2.
  if(psi.gt.2.*pi) wrr=wrr/2.
  if(psi.gt.3.*pi) wrr=wrr/2.
  if(psi.gt.4.*pi) wrr=wrr/2.
  r1=r+dpsi*wrr
  xiv(i,j+1)=r1*cos(psi)
  yiv(i,j+1)=r1*sin(psi)
  wz=wz(i)
  if(psi.gt.pi.and.i.eq.nlvr) wz=2.*wz
  ziv(i,j+1)=ziv(i,j)+wz*dpsi
  r=r1
  psi=psi
22 continue
30 continue
  if(iwrite.lt.2) goto 104
  do 92 j=1,nlva
    write(iwr,505) j
    write(iwr,510) (xiv(i,j),i=1,nlvr)
    write(iwr,510) (yiv(i,j),i=1,nlvr)
    write(iwr,510) (ziv(i,j),i=1,nlvr)
92 continue
104 continue
    return
    end

```

subroutine loop2(ktest)

C
C
C
C
C
C
C

This subroutine calculates the induced velocities at all the points in the near and intermediate wake. Only trailing segment elements are used. The wake is rolled up into three trailing vortices starting at the intermediate wake. Only the ends of the segments are considered -- the positions of the centers are never used or even calculated.

real k2
common/parm/lwr, lrd, lms, lmt, lmt2, niter, lwrite
common/geom/nbldst, nblds, sigma, fmu, etan(15), knnvr, etai(6), knivr,
 <twist, thetad(15), theta(15), thetac(14), theta0, thet0d, alphas,
 &cd0, cdk, dpsind, dpsin, dpsiid, dpsii, coeff, coeff1, c, s, blades,
 &nivr, nnva, nnvr1, nnva1, nnvr, nnca, etanv(15), etanc(16), nivr,
 &niva, nivr1, niva1, nivr, nica, etai(6), etaic(7),
 &ntva, ntva1, ntca, fps1, fps2
common/gamma/gamc(16), gamt(15), gamt1(3), gamtip, eta(3),
 &j1, kt(2), facgam
common/veloc/wxnv(15, 18), wynv(15, 18), wznv(15, 18), wxiv(6, 50), wyiv(6, 50),
 &wziv(6, 50), facgeom
common/vindo/lfar, nfar, x1, x2, y1, y2, z1, z2, x, y, z, facvel, gm, ux, uy, uz
common/posit/xnv(15, 18), ynv(15, 18), znv(15, 18), xiv(6, 50), yiv(6, 50),
 &ziv(6, 50)
common/save/wxnv(15, 18), wynv(15, 18), wznv(15, 18), wxivs(6, 50),
 &wyivs(6, 50), wzivs(6, 50)
common/self/iself
 common/extraspec/fps3

data twopi, fpi/6.28318, .079577/

TRAILING VORTEX STRENGTHS CALCULATED BY SUBROUTINE ROLLUP

call rollup(2)
if(lwrite.lt.1)goto 5
write(lwr, 100) niter
write(lwr, 123) (gamc(i), i=1, nnvr)
write(lwr, 123) (gamt(i), i=1, nnvr)
write(lwr, 123) (gamt1(i), i=1, nivr)
write(lwr, 110) (eta(i), i=1, 3)
continue

INITIALIZE ARRAYS FOR NEW INDUCED VELOCITIES

do 10 i=1, nnvr
do 10 j=1, nnva
 wxnv(i, j)=0.
 wynv(i, j)=0.
 wznv(i, j)=0.
10 continue
do 12 i=1, nivr
do 12 j=1, niva
 wxiv(i, j)=0.
 wyiv(i, j)=0.
 wziv(i, j)=0.
12 continue

VELOCITIES INDUCED BY BLADE BOUND CIRCULATION

x1=etanv(1)
y1=0.
z1=0.

```

y2=0.
z2=0.
do 20 i=1,nnvr-1
  x2=etanv(i+1)
  gm=ganc(i+1)
  n1=i
  n2=i+1
  call vindn(n1,n2,2)
  call vindi(n1,n2)
  x1=x2
20 continue
  if(iwrite.ne.2) goto 22
  do 21 j=1,nnva
    write(iwr,119) j
    write(iwr,120) (wxnv(k,j),k=1,nnvr)
    write(iwr,120) (wynv(k,j),k=1,nnvr)
    write(iwr,120) (wzmv(k,j),k=1,nnvr)
21 continue
  do 23 j=1,niva
    write(iwr,119) j
    write(iwr,120) (wxiv(i,j),i=1,nivr)
    write(iwr,120) (wyiv(i,j),i=1,nivr)
    write(iwr,120) (wziv(i,j),i=1,nivr)
23 continue
22 continue
C
C VELOCITIES INOUCED BY NEAR WAKE
C
dps2=fps2
do 30 i=1,nnvr
  fps2=fps1
  if(i.eq.nnvr-1) fps2=dps2
  do 30 j=1,nnva-1
    x1=xnv(i,j)
    y1=yv(i,j)
    z1=zv(i,j)
    x2=xnv(i,j+1)
    y2=yv(i,j+1)
    z2=zv(i,j+1)
    gm=gant(i)
    n1=(j-1)*nnvr+1
    n2=n1+nnvr
    call vindn(n1,n2,2)
    if(j+1.eq.nnva) n2=0
    call vindi(n1,n2)
30 continue
  fps2=dps2
  if(iwrite.ne.2) goto 32
  do 31 j=1,nnva
    write(iwr,119) j
    write(iwr,120) (wxnv(k,j),k=1,nnvr)
    write(iwr,120) (wynv(k,j),k=1,nnvr)
    write(iwr,120) (wzmv(k,j),k=1,nnvr)
31 continue
  do 33 j=1,niva
    write(iwr,119) j
    write(iwr,120) (wxiv(i,j),i=1,nivr)
    write(iwr,120) (wyiv(i,j),i=1,nivr)
    write(iwr,120) (wziv(i,j),i=1,nivr)
33 continue

```

```

32  continue
C
C  INTERMEDIATE WAKE
C
    phib=twopi/blades
    do 40 i=1,nivr
        if(i.eq.1) ksava=niva
        if(i.eq.2) ksava=niva
        if(i.eq.3) ksava=niva
    do 40 j=1,ksava-1
        x1=xiv(i,j)
        y1=yiv(i,j)
        z1=ziv(i,j)
        x2=xiv(i,j+1)
        y2=yiv(i,j+1)
        z2=ziv(i,j+1)
        gm=gamt1(i)
        dps2=fps2
        phi1=float(nnva-1)*dpsin + float(j-1)*dps11
        if(phi1.gt.phib-dpsin) fps2=fps3
        n1=(j-1)*nivr + nnva*nnvr + 1
        n2=n1+nivr
        if(j.eq.1) n1=0
        call vindn(n1,n2,2)
        call vind1(n1,n2)
        fps2=dps2
40  continue
    if(lwrite.ne.2) goto 42
    do 41 j=1,nnva
        write(lwr,119) j
        write(lwr,120) (wxnv(i,j),i=1,nnvr)
        write(lwr,120) (wynv(i,j),i=1,nnvr)
        write(lwr,120) (wzmv(i,j),i=1,nnvr)
41  continue
    do 43 j=1,niva
        write(lwr,119) j
        write(lwr,120) (wxiv(i,j),i=1,nivr)
        write(lwr,120) (wyiv(i,j),i=1,nivr)
        write(lwr,120) (wziv(i,j),i=1,nivr)
43  continue
42  continue
C
C  FAR WAKE
C
    if(lfar.eq.1) goto 45
    dz=ziv(nivr,niva)-ziv(nivr,niva-1)
    gm=gamt1p
    x1=xiv(nivr,niva)
    y1=yiv(nivr,niva)
    z1=ziv(nivr,niva)
    phi1=atan2(y1,x1)
    r=sqrt(x1*x1 + y1*y1)
    do 50 j=1,nfar
        phi1=phi1+dps11
        x2=r*cos(phi1)
        y2=r*sin(phi1)
        z2=z1+dz
        n1=j + nnva*nnvr + niva*nivr
        n2=n1+1
        call vindn(n1,n2,2)

```

```

      call vindl(n1,n2)
      x1=x2
      y1=y2
      z1=z2
50    continue
      goto 49
45    continue
      fkapa=phib/dpsii
      kapa=ifix(fkapa + .5)
      do 300 ki=1,nivr
      x1=xiv(ki,niva)
      y1=yiv(ki,niva)
      z1=ziv(ki,niva)+(ziv(ki,niva)-ziv(ki,niva-kapa))
      dgam=ganti(ki)/(ziv(ki,niva)-ziv(ki,niva-kapa))
      r=(sqrt(x1*x1 + y1*y1))
      do 46 i=1,nnvr
      do 46 j=1,nnva
      n=1
      x=xnv(i,j)
      y=yiv(i,j)
      z=ziv(i,j)
      z3=abs(z1-z)
      phi=atan2(y,x)
      eta3=sqrt(x*x + y*y)
      goto 200
210   continue
      wxnv(i,j)=wxnv(i,j) + wr*cos(phi)
      wynv(i,j)=wynv(i,j) + wr*sin(phi)
      wziv(i,j)=wziv(i,j) + wz
46    continue
      do 220 i=1,nivr
      if(i.eq.1) ksave=niva
      if(i.eq.2) ksave=niva
      if(i.eq.3) ksave=niva
      do 220 j=1,ksave
      n=2
      x=xiv(i,j)
      y=yiv(i,j)
      z=ziv(i,j)
      z3=abs(z1-z)
      phi=atan2(y,x)
      eta3=sqrt(x*x + y*y)
      goto 200
230   continue
      wxiv(i,j)=wxiv(i,j) + wr*cos(phi)
      wyiv(i,j)=wyiv(i,j) + wr*sin(phi)
      wziv(i,j)=wziv(i,j) + wz
220   continue
      if(iwrite.ne.2) goto 52
      do 51 j=1,nnva
      write(iwr,119) j
      write(iwr,120) (wxnv(i,j),i=1,nnvr)
      write(iwr,120) (wynv(i,j),i=1,nnvr)
      write(iwr,120) (wziv(i,j),i=1,nnvr)
51    continue
      do 53 j=1,niva
      write(iwr,119) j
      write(iwr,120) (wxiv(i,j),i=1,nivr)
      write(iwr,120) (wyiv(i,j),i=1,nivr)
      write(iwr,120) (wziv(i,j),i=1,nivr)

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53 continue
52 continue
300 continue
    goto 49
200 continue
    k2=4.*r*eta3/((r*eta3)**2 + z3**2)
    if(k2.eq.1.) goto 47
    f=alog(4./sqrt(1.-k2))
    e=1.+5*(f-.5)*(1.-k2) + .1875*(f-1.08333)*(1-k2)*(1-k2)
    capk=f+.25*(f-1.)*(1.-k2) + .14*(f-1.16666)*(1-k2)*(1-k2)
    goto 48
47 e=1.
    capk=10.
48 wr=-fpi*dgam*2.*sqrt(r/eta3/k2)*(capk*(2.-k2)-2.*e)
    psi=dpsin
    wz=0.
    do 250 k=1,2*kapa
        x3=r*r + eta3*eta3 + z3*z3 - 2.*r*eta3*cos(psi)
        wtemp=dpsin*(r*(r-eta3*cos(psi))/(eta3*eta3+r*r-2.*r*eta3*cos(psi)))
        wtemp=wtemp*(1.-(z3/sqrt(x3)))
        wz=wtemp + wz
        psi=psi+dpsin
250 continue
    wz=fpi*dgam*wz
    if(n.eq.1) goto 210
    if(n.eq.2) goto 230
    continue

```

C
C SELF-INDUCED VELOCITIES USING SCULLY APPROXIMATION
C

```

    if(lself.eq.0) goto 57
    if(lwrite.eq.2) write(1wr,150)
    do 54 i=1,nnvr
        do 54 j=1,nnva
            r=sqrt(xnv(i,j)**2+ynv(i,j)**2)
            dwz=fpi*gamti(i)*(alog(8.*r*tan(dpsin/4.)/fps2)-.25)/r
            wznv(i,j)=wznv(i,j)+dwz
54 continue
        do 55 i=1,nivr
            if(i.eq.1.or.i.eq.2) ksave=niva
            if(i.eq.3) ksave=niva
            do 55 j=1,ksave
                r=sqrt(xiv(i,j)**2+yiv(i,j)**2)
                dwz=fpi*gamti(i)*(alog(8.*r*tan(dpsin/4.)/fps2)-.25)/r
                wziv(i,j)=wziv(i,j)+dwz
55 continue
57 continue

```

C
C CONVERGENCE TEST AND NEXT APPROXIMATION
C

```

    ktest=1
    if(niter.eq.1) goto 69
    savevel=facvel
    do 67 i=1,nnvr
        do 67 j=1,nnva
            wxnv(i,j)=facvel*wxnv(i,j) + (1.-facvel)*wxnvs(i,j)
            wynv(i,j)=facvel*wynv(i,j) + (1.-facvel)*wynvs(i,j)
            wznv(i,j)=facvel*wznv(i,j) + (1.-facvel)*wznvs(i,j)
67 continue
        do 68 i=1,nivr

```


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```

do 68 j=1,niva
wxiv(1,j)=facvel*wxiv(1,j) + (1.-facvel)*wxivs(1,j)
wyiv(1,j)=facvel*wyiv(1,j) + (1.-facvel)*wyivs(1,j)
wziv(1,j)=facvel*wziv(1,j) + (1.-facvel)*wzivs(1,j)
68 continue
wconv=0.
do 1000 i=1,nnvr
wconv=wconv + abs(wznv(1,2))
1000 continue
wconv=wconv/float(nnvr)
facvel=savevel
ktest=0
do 60 i=1,nnvr
do 60 j=1,nnva
if(abs(wznv(1,j)-wznvs(1,j)).gt.(.02*abs(wconv))) ktest=1
if(ktest.eq.1) goto 66
60 continue
do 65 i=1,nivr
do 65 j=1,niva
if(abs(wziv(1,j)-wzivs(1,j)).gt.(.02*abs(wconv))) ktest=1
if(ktest.eq.1) goto 66
65 continue
66 continue
69 continue
do 203 i=1,nnvr
do 203 j=1,nnva
wxnv(1,j)=wxnv(1,j)
wynv(1,j)=wynv(1,j)
wznv(1,j)=wznv(1,j)
203 continue
do 204 i=1,nivr
do 204 j=1,niva
wxivs(1,j)=wxiv(1,j)
wyivs(1,j)=wyiv(1,j)
wzivs(1,j)=wziv(1,j)
204 continue
if(lwrite.lt.1)return
write(lwr,125)ktest,facvel
write(lwr,130)
do 80 j=1,nnva
write(lwr,119) j
write(lwr,120) (wxnv(1,j),i=1,nnvr)
write(lwr,120) (wynv(1,j),i=1,nnvr)
write(lwr,120) (wznv(1,j),i=1,nnvr)
80 continue
write(lwr,140)
do 90 j=1,niva
write(lwr,119) j
write(lwr,120) (wxiv(1,j),i=1,nivr)
write(lwr,120) (wyiv(1,j),i=1,nivr)
write(lwr,120) (wziv(1,j),i=1,nivr)
90 continue
return
100 format(/," LOOP2: ITERATION ".I4,/, " GAMC, GAMT, GAMTI, GAMTIP:")
123 format(2(9f10.6,/))
110 format(/," POSITIONS OF ROLLED-UP VORTICES:",3f10.6)
119 format(/,14)
120 format(2(9f10.6,/))
121 format(/,14,5x,f10.6)
125 format(/," LOOP2 CONVERGENCE ".I4," RELAXATION ".F5.2)

```

3. 2. 1. 0. 1. 2. 3.
10. 20. 30. 40. 50. 60. 70.

```
130 format(/.* NEAR WAKE INDUCED VELOCITIES:*)
140 format(/.* INTERMEDIATE WAKE INDUCED VELOCITIES:*)
150 format(/.* SCULLY CONTRIPUTION FOR EACH TRAILER: *)
end
```

subroutine rollup(ncall)

This subroutine calculates:

- a) the strengths of the trailing vortices in the near, intermediate and far wakes;
- b) in addition, the spanwise positions of the rolled up intermediate wake trailing vortices, interpolating an entire new intermediate wake (ncall=1) or just the first azimuthal position (ncall=3).

```
common/gamma/gamc(16),gamt(15),gamt(3),gamt(1),eta1,eta2,eta3,
&j1,j2,k3,facgam
common/parm/lwr,lr,lr2,lims,lim1,lim2,niter,lwrite
common/geom/nbls1,nbls2,sigma,fmu,etan(15),knnvr,eta1(6),knnvr,
&lt;twist,thetad(15),theta(15),thetac(14),theta0,thet0d,alphas,
&cd0,cdk,dpsind,dpsin,dpsid,dpsii,coeff,coeff1,c,s,blades,
&nivr,nva,nivr1,nva1,nncr,nncr,etanv(15),etanc(16),
&nivr,nva,nivr1,nva1,nncr,nncr,etaiv(6),etaic(7),
&ntva,ntva1,ntca,fps1,fps2
common/posit/xnv(15,18),ynv(15,18),znv(15,18),xiv(6,50),yiv(6,50),
&ziv(6,50)
```

CLEAR THE ARRAYS OF TRAILING VORTEX STRENGTHS

```
if(ncall.eq.3) goto 75
do 10 i=1,nivr
  gamt(i)=gamc(i+1)-gamc(i)
10 continue
do 15 i=1,3
  gamt(i)=0.
15 continue
```

FIND WHERE GAMC IS MAXIMUM NEAR THE TIP (GAMT CHANGES SIGN)
AND ROLL UP FROM THERE OUT TO TIP

```
gmax=0.
do 20 i=nncr,2,-1
  if(abs(gamc(i)).gt.gmax) gmax=abs(gamc(i))
  if(gmax.eq.abs(gamc(i))) j1=i
20 continue
30 continue
if(j1.gt.nivr) write(lwr,200)
200 format(//," Rollup: You screwed something up.")
do 40 i=j1,nivr
  gamt(i)=gamt(i)+gamc(i)
40 continue
```

FIND WHERE GAMT IS MINIMUM INBOARD AND ROLL UP ON EITHER SIDE
OF MINIMUM INTO TWO MORE TRAILING VORTICES

```
j2=2
j2=j1-3
if(nivr.eq.15) j2=j1-4
do 60 i=j2,j1-1
  gamt(i)=gamt(i)+gamc(i)
60 continue
do 70 i=j2,j1-1
  gamt(i)=gamt(i)+gamc(i)
70 continue
gamt(1)=gamt(1)+gamc(1)
```

```

      if(ncall.eq.1) return
C
C      FIND CENTROID OF EACH SECTION OF BLADE ROLLED UP
C
      eta1=0.
      eta2=0.
      eta3=0.
      do 80 i=1,j2-1
      eta1=eta1 + gamt(i)*etanv(i)
80      continue
      eta1=eta1/gamt(i)
      do 90 i=j2,j1-1
      eta2=eta2 + gamt(i)*etanv(i)
90      continue
      eta2=eta2/gamt(i)
      do 100 i=j1,nivr
      eta3=eta3 + gamt(i)*etanv(i)
100     continue
      eta3=eta3/gamt(i)
      if(niter.gt.1) return
C
C      CALCULATE INTERPOLATION FACTORS EITHER FOR NEAR WAKE (NCALL=3)
C      OR FOR INTERMEDIATE WAKE (NITER=1) AND INTERPOLATE NEW POSITIONS
C
      do 110 i=1,nivr
      if(eta1.ge.etaiv(i)) i1=i
      if(eta2.ge.etaiv(i)) i2=i
      if(eta3.ge.etaiv(i)) i3=i
110     continue
      terp1=(eta1-etaiv(i1))/(etaiv(i1+1)-etaiv(i1))
      terp2=(eta2-etaiv(i2))/(etaiv(i2+1)-etaiv(i2))
      terp3=(eta3-etaiv(i3))/(etaiv(i3+1)-etaiv(i3))
      do 140 j=1,niva
      xiv1=xiv(i1,j) + terp1*(xiv(i1+1,j)-xiv(i1,j))
      xiv2=xiv(i2,j) + terp2*(xiv(i2+1,j)-xiv(i2,j))
      xiv3=xiv(i3,j) + terp3*(xiv(i3+1,j)-xiv(i3,j))
      yiv1=yiv(i1,j) + terp1*(yiv(i1+1,j)-yiv(i1,j))
      yiv2=yiv(i2,j) + terp2*(yiv(i2+1,j)-yiv(i2,j))
      yiv3=yiv(i3,j) + terp3*(yiv(i3+1,j)-yiv(i3,j))
      ziv1=ziv(i1,j) + terp1*(ziv(i1+1,j)-ziv(i1,j))
      ziv2=ziv(i2,j) + terp2*(ziv(i2+1,j)-ziv(i2,j))
      ziv3=ziv(i3,j) + terp3*(ziv(i3+1,j)-ziv(i3,j))
      xiv(1,j)=xiv1
      xiv(2,j)=xiv2
      xiv(3,j)=xiv3
      yiv(1,j)=yiv1
      yiv(2,j)=yiv2
      yiv(3,j)=yiv3
      ziv(1,j)=ziv1
      ziv(2,j)=ziv2
      ziv(3,j)=ziv3
140     continue
      nivr=3
      nivr=nivr+1
      nivr1=nivr-1
      return
75     continue
      x=0.
      y=0.
      z=0.

```

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```

do 155 i=2,j2-1
  x=xnv(i,nnva)*gamt(i)+x
  y=ynv(i,nnva)*gamt(i)+y
  z=znv(i,nnva)*gamt(i)+z
155  continue
  xlv(1,1)=x/gamt(1)
  ylv(1,1)=y/gamt(1)
  zlv(1,1)=z/gamt(1)
  x=0.
  y=0.
  z=0.
  do 156 i=j2,j1-1
    x=xnv(i,nnva)*gamt(i)+x
    y=ynv(i,nnva)*gamt(i)+y
    z=znv(i,nnva)*gamt(i)+z
156  continue
    xlv(2,1)=x/gamt(2)
    ylv(2,1)=y/gamt(2)
    zlv(2,1)=z/gamt(2)
    x=0.
    y=0.
    z=0.
    do 157 i=j1,nnvr
      x=xnv(i,nnva)*gamt(i)+x
      y=ynv(i,nnva)*gamt(i)+y
      z=znv(i,nnva)*gamt(i)+z
157  continue
      xlv(3,1)=x/gamtip
      ylv(3,1)=y/gamtip
      zlv(3,1)=z/gamtip
return
end

```

XXXXXXXXXXXX

VELOCITIES INDUCED ON BLADE

300

C

```
entry vindn(n1,n2,loop)
```

```

      iskip=0
      nf=nnva
      if(n1.eq.0) nf=nnva-1
      if(loop.eq.1) nf=1
      do 20 i=1,nnvr
      do 20 j=1,nf
      x=xnv(i,j)
      y=ynv(i,j)
      z=znv(i,j)
      cc=1.
      ss=0.
      n3=(j-1)*nnvr + 1
      if(n1.eq.n3.or.n2.eq.n3) iskip=1
      do 20 k=1,nbls
      if(iskip.eq.1) goto 21
      call wxyz(fps2)
      wxnv(i,j)=wxnv(i,j) + (ux*cc + uy*ss)
      wynv(i,j)=wynv(i,j) + (uy*cc - ux*ss)
      wznv(i,j)=wznv(i,j) + uz
21    continue
      iskip=0
      sav=x
      x=x*c - y*s
      y=y*c + sav*s
      sav=cc
      cc=cc*c - ss*s
      ss=ss*c + sav*s
20    continue
      if(loop.eq.1) return
      if(n1.ne.0) return
      iskip=0
      do 26 i=1,nnvr
      x=xnv(i,nnva)
      y=ynv(i,nnva)
      z=znv(i,nnva)
      cc=1.
      ss=0.
      r=sqrt(x*x + y*y)
      r1=sqrt(x1*x1 + y1*y1)
      if(abs(r-r1).lt..025) iskip=1
      do 26 k=1,nbls
      if(iskip.eq.1) goto 28
      call wxyz(fps2)
      wxnv(i,nnva)=wxnv(i,nnva) + (ux*cc + uy*ss)
      wynv(i,nnva)=wynv(i,nnva) + (uy*cc - ux*ss)
      wznv(i,nnva)=wznv(i,nnva) + uz
28    continue
      iskip=0
      sav=x
      x=x*c - y*s
      y=y*c + sav*s
      sav=cc
      cc=cc*c - ss*s
      ss=ss*c + sav*s
26    continue
      return
C
C      VELOCITIES INDUCED ON INTERMEDIATE WAKE
C
      entry vindl(n1,n2)

```

```

      iskip=0
      nf=1
      if(n2.eq.0) nf=2
      do 30 i=1,nivr
         if(i.eq.1) ksave=niva
         if(i.eq.2) ksave=niva
         if(i.eq.3) ksave=niva
      do 30 j=nf,ksave
         x=xiv(i,j)
         y=yiv(i,j)
         z=ziv(i,j)
         cc=1.
         ss=0.
         n3=(j-1)*nivr + nnva*nnvr + 1
         if(n1.eq.n3.or.n2.eq.n3) iskip=1
         do 30 k=1,nbls
            if(iskip.eq.1) goto 31
            call wxyz(fps2)
            wxiv(i,j)=wxiv(i,j) + (ux*cc + uy*ss)
            wyiv(i,j)=wyiv(i,j) + (uy*cc - ux*ss)
            wziv(i,j)=wziv(i,j) + uz
31      continue
         iskip=0
         sav=x
         x=x*c - y*s
         y=y*c + sav*s
         sav=cc
         cc=cc*c - ss*s
         ss=ss*c + sav*s
30      continue
         if(n2.ne.0) return
         iskip=0
         do 35 i=1,nivr
            x=xiv(i,1)
            y=yiv(i,1)
            z=ziv(i,1)
            cc=1.
            ss=0.
            r=sqrt(x*x + y*y)
            r2=sqrt(x2*x2 + y2*y2)
            if(abs(r-r2).lt..025) iskip=1
            do 35 k=1,nbls
               if(iskip.eq.1) goto 36
               call wxyz(fps2)
               wxiv(i,1)=wxiv(i,1) + ux*cc + uy*ss
               wyiv(i,1)=wyiv(i,1) + uy*cc - ux*cc
               wziv(i,1)=wziv(i,1) + uz
36      continue
         iskip=0
         sav=x
         x=x*c - y*s
         y=y*c + sav*s
         sav=cc
         cc=cc*c - ss*s
         ss=ss*c + sav*s
35      continue
      return
end

```



```

C      subroutine wxyz(fps2)
C
C      This routine calculates the induced velocity due to any segment
C      of endpoints x1,y1,z1 and x2,y2,z2 and of strength gm on any
C      point x,y,z. It is only called by VIND.
C
      real*4 io
      common/vindo/lfar,nfar,x1,x2,y1,y2,z1,z2,x,y,z,facvel,gm,ux,uy,uz
      data fpi/.079577/
      xct=.5*(x1+x2)
      yct=.5*(y1+y2)
      zct=.5*(z1+z2)
      dxx=x-xct
      dyy=y-yct
      dzz=z-zct
      r12=sqrt((x1-x)**2+(y1-y)**2+(z1-z)**2)
      r22=sqrt((x2-x)**2+(y2-y)**2+(z2-z)**2)
      if(r12.le..1e-5.or.r22.le..1e-5) goto 100
      dsx=.5*(x2-x1)
      dsy=.5*(y2-y1)
      dsz=.5*(z2-z1)
      ds2=dsx**2 + dsy**2 + dsz**2
      fva=fps2*fps2*ds2
      rmax2=400.*ds2
      r02=dxx**2 + dyy**2 + dzz**2
      r03=r02*sqrt(r02)
      dsax=dsz*dyy - dsy*dzz
      dsmy=dsx*dzz - dsz*dxx
      dsxz=dsy*dxx - dsx*dyy
      dsm2=dsmx**2 + dsmy**2 + dsmz**2
      if(dsm2.le..1e-15) goto 100
      fvdz=fva/dsm2
      io=1.
      if(r02.gt.rmax2) goto 120
      a=-(dxx*dsx + dyy*dsy + dzz*dsz)/r02
      alpha2=ds2/r02
      alpaa=alpha2 - a*a
      if(abs(alpaa).le..1e-15) goto 110
      sq1a=sqrt(abs(1. + 2.*a + alpha2))
      sq2a=sqrt(abs(1. - 2.*a + alpha2))
      if(sq1a.lt..001) sq1a=.001
      if(sq1a.lt..001) sq1a=.001
      io=(alpha2 + a)/sq1a + (alpha2-a)/sq2a
      io=io/(2.*alpaa)
      goto 120
110    continue
      io=1./((1.-a*a)**2)
120    fact=-10*fpi*gm*2./r03
      fact=fact/(1.+fvdz)
      ux=fact*dsmx
      uy=fact*dsmy
      uz=fact*dsmz
      return
100    continue
      ux=0.
      uy=0.
      uz=0.
      return
      end

```

subroutine intgr(ktest)

This routine integrates the wake geometry using the induced velocities returned by LOOP2. Tangential and radial velocities are not used; the wake is integrated directly from wxnv, ynv and znv. The velocity of a wake node in travelling from position i,j to i,j+1 is assumed to be the average of the velocities at i,j and i,j+1.

```
common/parm/lwr,lr,lrms,lim1,lim2,niter,lwrite
common/geom/nbls1,nbls2,sigma,fmu,etan(15),knnvr,eta1(6),knivr,
&ltwist,thetad(15),theta(15),thetac(14),theta0,theta0d,alphas,
&cd0,cdk,dpsind,dpsin,dpsid,dpsil,coeff,coeff1,c,s,blades,
&nnvr,nnva,nnvr1,nnva1,nnvr,nnca,etanv(15),etanc(16),
&nivr,niva,nivr1,niva1,nicr,nica,etaiv(6),etaic(7),
&ntva,ntva1,ntca,fps1,fps2
common/posit/xnv(15,18),ynv(15,18),znv(15,18),xiv(6,50),
&yiv(6,50),ziv(6,50)
common/veloc/wxnv(15,18),wynv(15,18),wznv(15,18),wxiv(6,50),
&wyiv(6,50),wziv(6,50),facgeom
common/gamma/gamc(16),gamt(15),gamti(3),gamtip,etzi(3),k1,k2,k3,facgam
common/intgrsave/xnvs(15,18),ynvs(15,18),znvs(15,18),xivs(6,50),
&yivs(6,50),zivs(6,50)
common/special/ltgr
ktest=1
if(niter.eq.1) goto 203
do 10 i=1,nnvr
do 10 j=1,nnva
xnv(i,j)=0.
ynv(i,j)=0.
znv(i,j)=0.
10 continue
do 20 i=1,nnvr
xnv(i,1)=etanv(i)
ynv(i,1)=0.
znv(i,1)=0.
phi=0.
do 20 j=1,nnva-1
phi1=phi+dpsin
wr=(xnv(i,j)*cos(phi)+wxnv(i,j+1)*cos(phi1)+wynv(i,j)*sin(phi)+
&wynv(i,j+1)*sin(phi1))/2.
wt=(-wxnv(i,j)*sin(phi)-wxnv(i,j+1)*sin(phi1)+wynv(i,j)*cos(phi)+
&wynv(i,j+1)*cos(phi1))/2.
r=sqrt(xnv(i,j)**2 + ynv(i,j)**2)
r1=r+dpsin*wr
phi1=phi+dpsin*(2.*wt/(r+r1))+dpsin
xnv(i,j+1)=r1*cos(phi1)
ynv(i,j+1)=r1*sin(phi1)
znv(i,j+1)=znv(i,j) + dpsin*(wznv(i,j)+wznv(i,j+1))/2.
phi=phi1
20 continue
do 30 i=1,nivr
do 30 j=1,niva
xiv(i,j)=0.
yiv(i,j)=0.
ziv(i,j)=0.
30 continue
ncall=3
call rollup(ncall)
if(ltgr.ne.1.or.nnva.gt.2) goto 1033
```

```

do 1030 i=1,nnvr
  xnv(1,nnva)=xlv(nivr,1)
  ynv(1,nnva)=ylv(nivr,1)
  znv(1,nnva)=zlv(nivr,1)
1030 continue
1033 continue
c   zlv(nivr,1)=.025
do 40 i=1,nivr
  phi=atan2(ylv(1,1),xlv(1,1))
  do 40 j=1,niva-1
    phi1=phi+dps11
    wr=(wxlv(1,j)*cos(phi)+wxlv(1,j+1)*cos(phi1)+wyiv(1,j)*sin(phi)+
&wyiv(1,j+1)*sin(phi1))/2.
    wt=(-wxlv(1,j)*sin(phi)-wxlv(1,j+1)*sin(phi1)+wyiv(1,j)*cos(phi)+
&wyiv(1,j+1)*cos(phi1))/2.
    r=sqrt(xlv(1,j)**2 + ylv(1,j)**2)
    r1=r+dps11*wr
    phi1=phi+dps11+dps11*(2.*wt/(r+r1))
    xlv(1,j+1)=r1*cos(phi1)
    ylv(1,j+1)=r1*sin(phi1)
    zlv(1,j+1)=zlv(1,j) + dps11*(wzlv(1,j)+wzlv(1,j+1))/2.
    phi=phi1
40  continue
  savegeom=facgeom
  do 41 i=1,nnvr
    do 41 j=1,nnva
      xnv(1,j)=xnv(1,j)*facgeom + xnvs(1,j)*(1.-facgeom)
      ynv(1,j)=ynv(1,j)*facgeom + ynvs(1,j)*(1.-facgeom)
      znv(1,j)=zlv(1,j)*facgeom + znvs(1,j)*(1.-facgeom)
41  continue
    facgeom=savegeom
    do 42 i=1,nivr
      do 42 j=1,niva
        xlv(1,j)=xlv(1,j)*facgeom + xivs(1,j)*(1.-facgeom)
        ylv(1,j)=ylv(1,j)*facgeom + yivs(1,j)*(1.-facgeom)
        zlv(1,j)=zlv(1,j)*facgeom + zivs(1,j)*(1.-facgeom)
42  continue
    facgeom=savegeom
    ktest=0
    do 43 j=1,nnva
      zconv=0.
      do 1000 ii=1,nnvr-1
        zconv=zconv+abs(znv(ii,j))
1000 continue
      zconv=zconv/nnvr
      do 43 i=1,nnvr-1
        if(abs(znv(i,j)-znvs(i,j)).gt.(.02*zconv)) ktest=1
        if(ktest.eq.1) goto 53
43  continue
      do 44 i=1,nivr
        do 44 j=1,niva
          if(abs(zlv(i,j)-zivs(i,j)).gt..02*abs(zlv(i,j))) ktest=1
          if(ktest.eq.1) goto 53
44  continue
53  continue
203 continue
do 202 i=1,nnvr
  do 202 j=1,nnva
    xnvs(1,j)=xnv(1,j)
    ynvs(1,j)=ynv(1,j)

```

```

202  znvs(1,j)=znv(1,j)
      continue
      do 204 i=1,nivr
          if(i.eq.1.or.i.eq.2) ksave=niva
          if(i.eq.3) ksave=niva
      do 204 j=1,ksave
          xivs(1,j)=xiv(1,j)
          yivs(1,j)=yiv(1,j)
          zivs(1,j)=ziv(1,j)
204  continue
      if(iwrite.lt.1) goto 50
      write(iwr,100) ktest,facgeom
      do 45 j=1,nnva
          write(iwr,109) j
          write(iwr,110) (xnv(1,j),i=1,nnvr)
          write(iwr,110) (ynv(1,j),i=1,nnvr)
          write(iwr,110) (znv(1,j),i=1,nnvr)
45  continue
      do 46 j=1,niva
          write(iwr,109) j
          write(iwr,110) (xiv(1,j),i=1,nivr)
          write(iwr,110) (yiv(1,j),i=1,nivr)
          write(iwr,110) (ziv(1,j),i=1,nivr)
46  continue
50  return
100 format(//," INTGR CONVERGENCE ",i4," RELAXATION ",f10.5)
109 format(/,i4)
110 format(2(9f10.6,/))
      end

```

```

C      subroutine loop1(ktest)
C
C      This routine calculates a new distribution of bound circulation
C      gamc(1) consistent with the current wake geometry as given by
C      cw(1,1,n), by iteration.
C
C      INFLUENCE COEFFICIENTS CW(1,1,1)
C
      common/veloc/wxnv(15,18),wynv(15,18),wznv(15,18),wxiv(6,50),
      &wyiv(6,50),wziv(6,50),facgeom
      common/parm/lwr, lrd, lms, lim1, lim2, niter, lwrite
      common/geom/nbls1, nbls, sigma, fmu, etan(15), knnvr, etal(6), knivr,
      &lt;twist, thetad(15), theta(15), thetac(14), theta0, thet0d, alphas,
      &cd0, cdk, dpsind, dpsin, dpsid, dpsii, coeff, coeff1, c, s, blades,
      &nnvr, nnva, nnvr1, nnva1, nnvr, nnca, etanv(15), etanc(16),
      &nivr, niva, nivr1, niva1, nivr, nica, etalv(6), etalc(7),
      &ntva, ntva1, ntca, fps1, fps2
      common/gamma/gamc(16), gamt(15), gamt1(3), gamt1p, etal, eta2, eta3,
      &j1, kk(2), facgam
      common/vindo/lfar, nfar, x1, x2, y1, y2, z1, z2, x, y, z, facvel, gm, ux, uy, uz
      common/pos1t/xnv(15,18), ynv(15,18), znv(15,18), xiv(6,50),
      &yiv(6,50), ziv(6,50)
      common/coef/cwx(15,15,3), cwy(15,15,3), cwz(15,15,3)
      common/self/iself
      common/extraspec/fps3
      dimension gamcs(16)
      common/loopsave/wxv(16), wyv(16), wzv(16)
      data pi, twopi, fpi/3.14159, 6.28318, .079577/
      real k2
      do 5 i=1, nnvr
      do 5 j=1, nnvr
      do 5 n=1, 3
      cw(1, j, n)=0.
      cwy(1, j, n)=0.
      cwz(1, j, n)=0.
5      continue
      dps2=fps2
      do 10 i=1, nnvr
      fps2=fps1
      if(i.eq.nnvr-1) fps2=dps2
      do 11 j=1, nnva-1
      x1=xnv(i, j)
      y1=ynv(i, j)
      z1=znv(i, j)
      x2=xnv(i, j+1)
      y2=ynv(i, j+1)
      z2=znv(i, j+1)
      n1=(j-1)*nnvr + 1
      n2=n1+nnvr
      gm=1.
      call vindb(n1, n2, 1, 1)
      continue
11      continue
10      fps2=dps2
      phib=twopi/blades
      do 20 i=1, nivr
      if(i.eq.1) ksave=niva
      if(i.eq.2) ksave=niva
      if(i.eq.3) ksave=niva
      do 21 j=1, ksave-1

```

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```

x1=xiv(1,j)
y1=yiv(1,j)
z1=ziv(1,j)
x2=xiv(1,j+1)
y2=yiv(1,j+1)
z2=ziv(1,j+1)
n1=(j-1)*nivr + nnvr*nnva + 1
n2=n1+nivr
dps2=fps2
ph11=float(nnva-1)*dpsin + float(j-1)*dps11
if(ph11.gt.ph1b-dpsin) fps2=fps3
gm=1.
call vindb(n1,n2,1,2)
fps2=dps2
21 continue
20 continue
n=3
if(ifar.eq.1) goto 401
dz=ziv(nivr,niva)-ziv(nivr,niva-1)
x1=xiv(nivr,niva)
y1=yiv(nivr,niva)
z1=ziv(nivr,niva)
psi=atan2(y1,x1)
r=sqrt(x1*x1 + y1*y1)
do 30 j=1,nfar
psi=psi+dps11
x2=r*cos(psi)
y2=r*sin(psi)
z2=z1+dz
n1=j + nnva*nnvr + niva=nivr
n2=n1+1
gm=1.
call vindb(n1,n2,1,3)
x1=x2
y1=y2
z1=z2
30 continue
goto 301
401 continue
fkapa=ph1b/dps11
kapa=ifix(fkapa + .5)
do 505 k1=1,nivr
x1=xiv(k1,niva)
y1=yiv(k1,niva)
z1=ziv(k1,niva)+(ziv(k1,niva)-ziv(k1,niva-kapa))
dgam=1./((ziv(k1,niva)-ziv(k1,niva-kapa))
r=(sqrt(x1*x1+y1*y1))
do 201 i=1,nnvr-1
x=(etanv(i)+etanv(i+1))/2.
y=0.
z=0.
z3=abs(z1-z)
eta3=sqrt(x*x+y*y)
k2=4.*eta3/((r+eta3)**2+z3**2)
if(k2.eq.1.) goto 202
f=alog(4./sqrt(1.-k2))
e=1+.5*(f-.5)*(1.-k2) + .1875*(f-1.08333)*(1.-k2)=(1.-k2)
capk=f+.25*(f-1.)*(1.-k2)+.14*(f-1.13666)*(1.-k2)*(1.-k2)
goto 203
e=1.

```

```
203 capk=10.  
continue  
wr=-fp1*dgam*2.*sqrt(r/eta3/k2)*(capk*(2.-k2)-2.*e)  
psi=dpsin  
wz=0.  
do 204 k=1,2*kapa  
x3=r*r + eta3*eta3 + z3*z3 - 2.*r*eta3*cos(psi)  
wtemp=dps11*r*(r-eta3*cos(psi))/(eta3*eta3+r*r-2.*r*eta3*cos(psi))  
wtemp=wtemp*(1.-(z3/sqrt(x3)))  
wz=wz+wtemp  
psi=psi+dps11  
204 continue  
wz=wz+fp1*dgam  
cwx(1,kl,n)=cwx(1,kl,n)+wr  
cwz(1,kl,n)=cwz(1,kl,n)+wz  
201 continue  
505 continue  
C  
C Loop on gamc(i). First clear array of blade induced velocities.  
C Then calculate new wxv,wyv,wzv from influence coefficients.  
C Then new gamc. Back to beginning until converged.  
C  
301 continue  
if(lwrto.eq.2) write(lwr,304)  
ktemp=0  
do 200 k=1,lim1  
savegam=facgam  
1000 continue  
do 35 i=1,nnvr  
wxv(i)=0.  
wyv(i)=0.  
wzv(i)=0.  
35 continue  
do 36 j=1,nnvr  
do 37 i=1,nnvr-1  
wxv(i)=wxv(i) + cwx(1,j,1)*gamt(j)  
wyv(i)=wyv(i) + cwy(1,j,1)*gamt(j)  
wzv(i)=wzv(i) + cwz(1,j,1)*gamt(j)  
37 continue  
c if(ktemp.eq.1) write(lwr,310) (wzv(k),k=1,nnvr)  
36 continue  
do 40 j=1,nivr  
do 41 i=1,nnvr-1  
wxv(i)=wxv(i) + cwx(1,j,2)*gamt1(j)  
wyv(i)=wyv(i) + cwy(1,j,2)*gamt1(j)  
wzv(i)=wzv(i) + cwz(1,j,2)*gamt1(j)  
41 continue  
c if(ktemp.eq.1) write(lwr,310) (wzv(k),k=1,nnvr)  
40 continue  
do 50 j=1,nivr  
do 51 i=1,nnvr-1  
wxv(i)=wxv(i) + cwx(1,j,3)*gamt1(j)  
wyv(i)=wyv(i) + cwy(1,j,3)*gamt1(j)  
wzv(i)=wzv(i) + cwz(1,j,3)*gamt1(j)  
51 continue  
c if(ktemp.eq.1) write(lwr,310) (wzv(k),k=1,nnvr)  
50 continue  
c if(ktemp.eq.1) goto 1001  
c if(iself.eq.0) goto 55  
c do 56 i=1,nnvr
```

```

C      r=etanv(i)
C      dwz=fpi*gamc(i)=(alog(8.*r*tan(dpsin/4.)/fps2)-.25)/r
C      wzv(i)=wzv(i)+dwz
C 56      continue
55      continue
      gamc(i)=0.
      gamc(nncr)=0.
      do 70 i=1,nncr-1
      wz=(wzv(i)+fmu)
      wy=wyv(i) + (etanv(i)+etanv(i+1))/2.
      tlam=wz/wy
      flamda=atan(tlam)
      u=sqrt(wz**2 + wy**2)
      alp=flamda - thetac(i)
      if(alp.gt.alphas) alp=alphas
      gamc(i+1)=pi*pi*sigma*u*alp/blades
70      continue
      gamc(nncr)=gamc(nncr)*coeff1

C
C      CONVERGENCE TEST
C
      ktest=1
      if(k.eq.1) goto 94
      ktest=0
      do 80 i=1,nncr
      if(abs(gamc(i)-gamcs(i)).gt.0.1*abs(gamc(i))) ktest=1
      if(ktest.eq.1) goto 81
80      continue
81      continue
      do 90 i=1,nncr
      gamc(i)=gamc(i)*facgam + gamcs(i)*(1.-facgam)
90      continue
94      continue
      if(ktest.eq.0) ktemp=1
      if(ktest.eq.0) goto 1000
1001      continue
      if(iwrite.ne.2.and.ktest.ne.0) goto 52
      if(iwrite.lt.1) goto 52
      write(iwr,311) k
      write(iwr,310) (gamc(i),i=1,nncr)
      write(iwr,310) (wxv(i),i=1,nncr)
      write(iwr,310) (wyv(i),i=1,nncr)
      write(iwr,310) (wzv(i),i=1,nncr)
52      continue
      do 91 i=1,nncr
      gamcs(i)=gamc(i)
91      continue
      call rollup(1)
      if(ktest.eq.0) goto 205
200      continue
205      continue
      facgam=savegam
      if(ktest.eq.1)write(iwr,300)
      if(ktest.eq.0.and.iwrite.gt.0) write(iwr,305) k
311      format(/,i4)
310      format(2(9f10.6,/))
304      format(///," LOOP1 RESULTS",/)
300      format(///," LOOP1: NO CONVERGENCE")
305      format(///," LOOP1: CONVERGED IN ",i4," ITERATIONS")
400      return
```


SAMPLE OUTPUT

```

*** INPUT *** CASE # : 1
NUMBER OF BLADES 2
SIGMA 0.04640
MU 0.00000
PITCH ANGLE DISTRIBUTION(DG): 17.50000 15.30000 14.20000 12.55000 10.90000
9.25000 8.70000 8.15000 7.93000 7.71000 7.49000
7.27000 7.05000
STALL ANGLE 0.20000
CD=.0140+0.500*ALPHA**2
MAX. NUMBER OF ITERATIONS FOR LOOP1 AND LOOP2: 20 200
CORE SIZE FOR NEAR WAKE INSDARD: 0.050 TIP: 0.010
NEAR WAKE DEFINITION:(13, 8), 0.10000 0.25000 0.35000 0.50000
0.65000 0.80000 0.85000 0.90000 0.92000 0.94000
0.96000 0.98000 1.00000
INT. WAKE DEFINITION:( 6,38), 0.10000 0.25000 0.60000 0.85000
0.95000 1.00000
CORE BURST TO 0.05
TIP COEFFICIENT 0.00

```

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MAIN RESULTS -- CONVERGENCE: 0

CT= -0.004533 CP= 0.000337

GANC,WXC,WYC,WZC:

-0.00628	-0.01043	-0.01269	-0.01391	-0.01533	-0.01725	-0.01989	-0.02106	-0.02119	-0.01932	-0.01443	0.00000	GANC
0.00125	0.00365	0.00491	-0.01000	-0.02830	-0.05013	-0.05587	-0.04742	-0.04134	-0.03603	-0.03172	-0.02829	WXC
-0.00037	-0.00123	-0.00233	-0.00287	-0.00276	-0.00262	-0.00225	-0.00140	-0.00080	-0.00034	-0.00005	0.00085	WYC
0.02283	0.03163	0.04364	0.05684	0.06046	0.05373	0.04163	0.03588	0.03439	0.04172	0.06219	-0.05524	WZC

WAKE GEOMETRY:

1	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	0.000	PSI
	0.10000	0.25000	0.35000	0.50000	0.65000	0.80000	0.85000	0.90000	0.92000	0.94000	0.96000	0.98000	R
	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	0.00000	Z
2	9.803	9.889	9.891	9.913	9.941	9.958	9.960	9.977	9.982	9.991	10.007	10.008	10.003
	0.09999	0.25054	0.35094	0.49951	0.64669	0.79268	0.84057	0.89125	0.91248	0.93420	0.95958	0.97439	0.99061
	0.00398	0.00661	0.00868	0.01123	0.01212	0.01194	0.01158	0.00948	0.00984	0.01046	0.01271	0.00098	-0.00981
3	19.464	19.739	19.755	19.812	19.872	19.911	19.911	19.949	19.961	19.983	20.035	20.011	19.997
	0.09991	0.25101	0.35182	0.49899	0.64341	0.78559	0.83145	0.88260	0.90572	0.93072	0.96796	0.96817	0.97260
	0.00890	0.01438	0.01865	0.02361	0.02537	0.02513	0.02550	0.02170	0.02260	0.02373	0.02143	0.00302	-0.01650
4	29.273	29.633	29.663	29.731	29.814	29.871	29.887	29.927	29.948	29.988	30.078	30.017	29.969
	0.09982	0.25149	0.35270	0.49851	0.64019	0.77881	0.82272	0.87459	0.89975	0.92961	0.97575	0.96176	0.95108
	0.01270	0.02043	0.02699	0.03476	0.03765	0.03761	0.03912	0.03332	0.03429	0.03497	0.01631	0.00562	-0.01114
5	39.186	39.602	39.594	39.681	39.762	39.836	39.824	39.908	39.942	40.003	40.101	40.023	39.943
	0.09978	0.25200	0.35358	0.49807	0.63705	0.77238	0.81441	0.86691	0.89450	0.93051	0.97308	0.95581	0.93606
	0.01594	0.02575	0.03470	0.04549	0.04967	0.04991	0.05295	0.04472	0.04520	0.04422	0.00390	0.00881	0.00558
6	49.141	49.570	49.541	49.597	49.714	49.805	49.782	49.891	49.939	50.024	50.097	50.030	49.939
	0.09979	0.25255	0.35448	0.49767	0.63400	0.76630	0.80654	0.85943	0.88981	0.93308	0.95841	0.95051	0.93368
	0.01886	0.03062	0.04200	0.05606	0.06161	0.05215	0.06704	0.05605	0.05539	0.05127	-0.00503	0.01202	0.02442
7	59.121	59.554	59.502	59.536	59.668	59.777	59.740	59.874	59.940	60.052	60.070	60.039	59.963
	0.09985	0.25315	0.35539	0.49729	0.63104	0.76060	0.79910	0.85218	0.88557	0.93681	0.93792	0.94548	0.94085
	0.02154	0.03511	0.04879	0.06665	0.07359	0.07442	0.08147	0.08735	0.08491	0.05399	-0.00296	0.01480	0.03558
8	69.115	69.551	69.481	69.468	69.623	69.754	69.702	69.861	69.952	70.032	70.059	70.046	69.973
	0.09994	0.25380	0.35636	0.49682	0.62819	0.75526	0.79222	0.84529	0.88202	0.93856	0.92211	0.94027	0.94701
	0.02403	0.03921	0.05477	0.07787	0.08572	0.08650	0.09614	0.07904	0.07392	0.05847	0.00520	0.01730	0.03807
9	69.602	69.760	70.050										
	0.43726	0.81049	0.93590										
	0.06098	0.09036	0.01840										

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2
89.520 89.694 90.056
0.43903 0.79760 0.92485
0.07532 0.11895 0.02570

3
109.444 109.660 110.072
0.44082 0.78718 0.91416
0.08936 0.14845 0.03339

4
129.350 129.658 130.114
0.44268 0.77875 0.90374
0.10304 0.17848 0.04153

5
149.209 149.663 150.187
0.44459 0.77222 0.89352
0.11636 0.20866 0.04987

6
168.963 169.621 170.281
0.44639 0.76754 0.88370
0.12953 0.23887 0.05741

7
188.393 189.413 190.262
0.44710 0.76425 0.87492
0.14491 0.27038 0.07239

8
207.821 209.187 210.184
0.44672 0.76190 0.86721
0.16268 0.30292 0.09449

9
227.568 229.043 230.179
0.44618 0.76019 0.86001
0.18045 0.33470 0.11490

10
247.418 248.940 250.166
0.44528 0.75872 0.85346
0.19785 0.36537 0.13454

11
267.288 268.870 270.157
0.44368 0.75773 0.84785
0.21500 0.39489 0.15368

12
287.189 288.825 290.155
0.44184 0.75765 0.84305
0.23179 0.42339 0.17245

13
307.104 308.756 310.158
0.44023 0.75803 0.83872
0.24813 0.45126 0.18093

PSI=180: Z(TIP)=0.061
R(TIP)=0.879

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14
 326.999 328.674 330.166
 0.43888 0.75821 0.83469
 0.26419 0.47907 0.20873

15
 346.825 348.578 350.160
 0.43761 0.75814 0.83099
 0.28040 0.50738 0.22610

16
 366.533 368.455 370.044
 0.43603 0.75795 0.82756
 0.29741 0.53676 0.24464

17
 386.215 388.318 389.928
 0.43400 0.75788 0.82438
 0.31532 0.56732 0.26463

18
 405.983 408.187 409.888
 0.43182 0.75829 0.82141
 0.33352 0.59868 0.28437

19
 425.811 428.069 429.863
 0.42968 0.75944 0.81866
 0.35160 0.63029 0.30354

20
 445.667 447.978 449.857
 0.42755 0.76100 0.81659
 0.36936 0.65926 0.32219

21
 465.548 467.898 469.864
 0.42548 0.76164 0.81547
 0.38668 0.68215 0.34040

22
 485.450 487.845 489.853
 0.42354 0.76085 0.81484
 0.40365 0.70163 0.35824

23
 505.350 507.803 509.830
 0.42174 0.75906 0.81418
 0.42048 0.72158 0.37579

24
 525.219 527.780 529.791
 0.41996 0.75623 0.81342
 0.43749 0.74248 0.39341

25
 545.040 547.780 549.713
 0.41803 0.75233 0.81253
 0.45494 0.76469 0.41172

PSI-380: Z(TIP)=0.235
 R(TIP)=0.829

PSI-540: Z(TIP)=0.402
 R(TIP)=0.813

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26
 564.840 567.791 569.637
 0.41592 0.74754 0.81142
 0.47290 0.78845 0.43077

27
 584.655 587.789 589.598
 0.41378 0.74225 0.81007
 0.49115 0.81364 0.44999

28
 604.490 607.760 609.574
 0.41166 0.73691 0.80851
 0.50941 0.83879 0.46907

29
 624.333 627.704 629.571
 0.40924 0.73095 0.80808
 0.52732 0.86195 0.48780

30
 644.182 647.640 649.597
 0.40613 0.72367 0.81007
 0.54453 0.88270 0.50595

31
 664.087 667.653 669.560
 0.40263 0.71605 0.81327
 0.56120 0.90171 0.52358

32
 684.031 687.708 689.498
 0.39916 0.70918 0.81628
 0.57767 0.91969 0.54096

33
 703.982 707.775 709.421
 0.39579 0.70310 0.81902
 0.59418 0.93690 0.55837

34
 723.915 727.828 729.329
 0.39247 0.69773 0.82147
 0.61089 0.95347 0.57609

35
 743.825 747.850 749.246
 0.38922 0.69300 0.82365
 0.62784 0.96945 0.59412

36
 763.719 767.848 769.194
 0.38614 0.68882 0.82553
 0.64494 0.98481 0.61215

37
 783.607 787.826 789.160
 0.38334 0.68503 0.82708
 0.66204 0.99948 0.62993

PSI-720: Z(TIP)=0.567
 R(TIP)=0.820

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 OF POOR QUALITY